Overview of Complex Analysis (Gamelin)

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This is a condensed version of Theodore W. Gamelin's *Complex Analysis* containing only definitions, propositions, theorems, etc. For proofs and detailed explanations, refer to the actual text.

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1 The Complex Plane and Elementary Functions

1.1 Complex Numbers

Definition 1.1. A complex number is an expression of the form z = x + iy where x and y are real numbers. The component x the real part of z and y the imaginary part of z. We will denote these with

$$x = \operatorname{Re} z$$
 $y = \operatorname{Im} z$.

The set of all complex numbers is called the **complex plane** and denote it with \mathbb{C} . There exists a one-to-one correspondence between the complex numbers and points in the Euclidean plane \mathbb{R}^2 :

$$z = x + iy \longleftrightarrow (x, y).$$

The real numbers correspond to the x-axis in the Euclidean plane while the **purely imaginary numbers** correspond to the y-axis and are of the form iy. The purely imaginary numbers form the **imaginary axis** $i\mathbb{R}$.

We add complex numbers by adding their real and imaginary parts separately.

$$(x + iy) + (u + iv) = (x + u) + i(y + v).$$

Thus, $\operatorname{Re}(z+w) = \operatorname{Re} z + \operatorname{Re} w$ and $\operatorname{Im}(z+w) = \operatorname{Im} z + \operatorname{Im} w$. The addition of complex numbers corresponds to the addition of vectors in the Euclidean plane

Definition 1.2. The modulus of a complex number z = x + iy is the length $\sqrt{x^2 + y^2}$ of the corresponding vector in the Euclidean plane. The modulus is also called the **absolute value** of z.

Lemma 1.3 (Triangle Inequality). The triangle inequality for vectors in the plane takes the form

$$|z+w| \le |z| + |w|, \qquad z, w \in \mathbb{C}.$$

Similarly, we have the related inequality

$$|z - w| \ge |z| - |w|, \qquad z, w \in \mathbb{C}.$$
(1.1)

Definition 1.4. Complex numbers can be multiplied, a feature that distinguishes the complex plane \mathbb{C} from the Euclidean plane \mathbb{R}^2 . Formally, complex multiplication is defined by

$$(x+iy)(u+iv) = xu - yv + i(xv + yu).$$

The usual laws of multiplication hold true:

$$(z_1z_2)z_3 = z_1(z_2z_3),$$
 (associative law)

$$z_1z_2 = z_2z_1,$$
 (commutative law)

$$z_1(z_2 + z_3) = z_1z_2 + z_1z_3.$$
 (distributive law)

With respect to algebraic operations, complex numbers behave the same as real numbers, but complex numbers require the special rule $i^2 = -1$.

Definition 1.5. Every complex number $z \neq 0$ has a multiplicative inverse 1/z which is given explicitly by

$$\frac{1}{z} = \frac{x - iy}{x^2 + y^2}, \qquad z = x + iy \in \mathbb{C}, z \neq 0.$$

Definition 1.6. The complex conjugate of a complex number z = x + iy is defined to be z = x - iy. Geometrically speaking, it is the reflection of z across the x-axis in the Euclidean plane.

Lemma 1.7. The following are useful identities involving conjugates:

$$\begin{split} \overline{\overline{z}} &= z, & z \in \mathbb{C}, \\ \overline{z + w} &= \overline{z} + \overline{w}, & z, w \in \mathbb{C}, \\ \overline{zw} &= \overline{zw}, & z, w \in \mathbb{C}, \\ |z| &= |\overline{z}|, & z \in \mathbb{C}, \\ |z|^2 &= z\overline{z}, & z \in \mathbb{C}. \end{split}$$

We can rewrite the 1/z in terms of the complex conjugate of z:

$$1/z = \overline{z}/|z|^2, \qquad z \in \mathbb{C}, z \neq 0.$$

The real and imaginary parts of z can be recovered using complex conjugates:

Re
$$z = (z + \overline{z})/2$$
, Im $z = (z - \overline{z})/2i$, $z \in \mathbb{C}$.

From $|zw|^2 = (zw)(\overline{zw}) = (z\overline{z})(w\overline{w}) = |z|^2|w|^2$, we obtain:

$$|zw| = |z||w|.$$

Definition 1.8. A complex polynomial of degree $n \ge 0$ is a function of the form

$$p(z) = a_n z^n + a_{n-1} z^{n-1} + \ldots + a_1 z + a_0, \qquad z \in \mathbb{C}.$$

where a_0, \ldots, a_n are complex numbers and $a_n \neq 0$.

Theorem 1.9 (Fundamental Theorem of Algebra). Every polynomial p(z) of degree $n \ge 1$ has a factorization

$$p(z) = c(z - z_1)^{m_1} \cdots (z - z_k)^{m_k}$$

where the z_i 's are unique and $m_j \ge 1$. This factorization is unique, up to a permutation of the factors.

Definition 1.10. The points z_1, \ldots, z_k in the preceding theorem are uniquely characterized as the **zeros** of p(z), or the **roots** of the equation p(z) = 0. The integer m_j is characterized as the unique integer m with the property that p(z) can be factored as $(z - z_j)^m q(z)$ where q(z) is a polynomial satisfying $q(z_j) \neq 0$.

1.2 Polar Representation

Definition 1.11. Since any point $(x, y) \neq (0, 0)$ in the plane can be represented by polar coordinates r and θ where $r = \sqrt{x^2 + y^2}$ and θ is the angle subtended by (x, y) and the x-axis, we can also express complex numbers using polar coordinates.

$$z = x + iy = r(\cos\theta + \sin\theta).$$

Here r = |z| is the modulus of z. We define the **argument** of z to be the angle θ and we write

$$\theta = \arg z.$$

Thus arg z is a multi-valued function, defined for $z \neq 0$. The **principal value of** arg z, denoted Arg z, is the value of θ within $-\pi < \theta \leq \pi$. The values of arg z are obtained by adding integer multiples of 2π to Arg z:

$$\arg z = \{ \operatorname{Arg} z + 2\pi k : k = 0, \pm 1, \pm 2, \ldots \}, \qquad z \neq 0.$$

It will be convenient to introduce the notation

$$e^{i\theta} = \cos\theta + i\sin\theta. \tag{1.2}$$

From (1.2), we obtain

$$z = re^{i\theta}$$
 $r = |z|, \ \theta = \arg z.$

This representation is the **polar representation** of z. Since $e^{i\theta} = \cos\theta + i\sin\theta$, $e^{i\theta}$ is also 2π -periodic, so

$$e^{i(\theta+2\pi m)} = e^{i\theta}, \qquad m = 0, \pm 1, \pm 2, \dots$$

and

$$e^{2\pi m i} = 1,$$
 $m = 0, \pm 1, \pm 2, \dots$

Lemma 1.12. Some useful identities satisfied by the exponential function are

$$|e^{i\theta}| = 1, \tag{1.3}$$

$$\overline{e^{i\theta}} = e^{-i\theta},\tag{1.4}$$

$$1/e^{i\theta} = e^{-i\theta}.\tag{1.5}$$

Definition 1.13. An important property of the exponential function is the addition formula:

$$e^{i(\theta+\varphi)} = e^{i\theta}e^{i\varphi}, \qquad -\infty < \theta, \varphi < \infty.$$
(1.6)

This is equivalent to

$$\cos(\theta + \varphi) + i\sin(\theta + \varphi) = (\cos\theta + i\sin\theta)(\cos\varphi + i\sin\varphi).$$

Equating the real and imaginary components on either side, we obtain the addition formulae for sine and cosine:

$$\cos(\theta + \varphi) = \cos\theta\cos\varphi - \sin\theta\sin\varphi, \qquad (1.7)$$

$$\sin(\theta + \varphi) = \cos\theta \sin\varphi + \sin\theta \cos\varphi. \tag{1.8}$$

Thus (1.3), (1.4), and (1.5) can be rewritten to

$$\arg \overline{z} = -\arg z,\tag{1.9}$$

$$\arg(1/z) = -\arg z,\tag{1.10}$$

$$\arg(z_1 z_2) = \arg z_1 + \arg z_2.$$
 (1.11)

If we let $z_1 = r_1 e^{i\theta_1}$ and $z_2 = r_2 e^{i\theta_2}$, then we can use the addition formula and write multiplication in polar form:

$$z_1 z_2 = r_1 r_2 e^{i\theta_1} e^{i\theta_2} = r_1 r_2 e^{i(\theta_1 + \theta_2)}.$$

Definition 1.14. The addition formula also allows use to derive formulas for $\cos n\theta$ and $\sin n\theta$ in terms of $\cos \theta$ and $\sin \theta$. Thus

$$\cos n\theta + i\sin n\theta = e^{in\theta} = \left(e^{i\theta}\right)^n = \left(\cos \theta + i\sin \theta\right)^n.$$

By equating $\cos n\theta$ with the real terms and $\sin n\theta$ with the imaginary terms, we produce identities that are known as **de Moivre's formulae**.

Definition 1.15. A complex number z is an **nth root** of w if $z^n = w$. The nth roots of w are precisely the roots of the polynomial $z^n - w$. The roots are given explicitly by

$$r = \rho^{1/n},$$

$$\theta = \frac{\varphi}{n} + \frac{2\pi k}{n}, \qquad k = 0, 1, 2, \dots, n-1.$$

where we take the usual positive root of ρ . Since these *n* roots are distinct, and there at most *n* nth roots, this list includes all the *n*th roots of *w*. Graphically, the roots are distributed equally around the circle centered at 0 with radius $|w|^{1/n}$.

Definition 1.16. The *n*th roots of 1 are also called the *n*th roots of unity and are given explicitly by:

$$\omega_k = e^{2\pi i k/n}, \qquad 0 \le k \le n-1.$$

1.3 Stereographic Projection

Definition 1.17. The extended complex plane is the complex plane together with the point at infinity. We denote the extended complex plane by \mathbb{C}^* , so that $\mathbb{C}^* = \mathbb{C} \cup \{\infty\}$. We can visualize the extended complex plane through the stereographic projection.

Definition 1.18. Let P = (X, Y, Z) be any point on the unit sphere other than the north pole N = (0, 0, 1). If we draw a straight line thrown N and P, the *stereographic projection* of P is the point $z = (x+iy) \sim (x, y, 0)$ where the straight line meets the coordinate plane at Z = 0. We can think of the stereographic projection as a map from the unit sphere in three-dimensional Euclidean space \mathbb{R}^3 to the extended complex plane. The stereographic projection of the north pole is defined to be ∞ , the point at infinity.

An explicit formula for the stereographic projection can be derived as follows. Let L be the line throw P and N parameterically by N + t(P - N) where $-\infty < t < \infty$. Then the line meets the (x, y)-plane at poin (x, y, 0) which satisfies

$$(x, y, 0) = (tX, tY, t(Z - 1))$$

for some parameter value t. Equating the two sides, we get

$$\begin{cases} x &= tX = X/(1-Z), \\ y &= tY = Y/(1-Z). \end{cases}$$

From the equation of the sphere $X^2 + Y^2 + Z^2 = 1$, we get

$$t = \frac{1}{2}(|z|^2 + 1)$$

which yields

$$\begin{cases} X &= 2x/(|z|^2 + 1), \\ Y &= 2y/(|z|^2 + 1), \\ Z &= (|z|^2 - 1)/(|z|^2 + 1). \end{cases}$$

The point (X, Y, Z) on the sphere is deterimed uniquely by the point z = x + iy of the plane. Thus there is a one-to-one correspondence between points P on the sphere, except the north pole N, and points z = z + iy of the complex plane.

Theorem 1.19. Under the stereographic projection, circles on the sphere correspond to circles and straight lines in the plane.

Definition 1.20. By the previous theorem, any straight line in the complex plane can be thought of as a circle through ∞ .

1.4 The Square and Square Root Functions

Definition 1.21. The square function, $w = z^2$, is better understood in polar form. From the polar decomposition $w = z^2 = r^2 e^{2i\theta}$, we have

$$|w| = |z|^2,$$

arg $w = 2 \arg z.$

Definition 1.22. Finding the inverse function for $w = z^2$ is more difficult. Every number $w \neq 0$ is mapped by exactly two values of z, the square roots $\pm \sqrt{w}$. In order to define an inverse function, we must restrict the domain in the z-plane so that each w is mapped to by exactly one z.

All the values in the right half the z-plane map to the entire w-plane. Thus we can draw a **slit** or **branch cut** along the negative real axis from $-\infty$ to 0, and we can define the inverse function on the **slit plane** $\mathbb{C} \setminus (-\infty, 0]$.

Definition 1.23. We refer to the determination of the inverse function as the **branch** of the inverse. One branch $f_1(w)$ of the inverse function is defined by declaring $f_1(w)$ the value z such that $\operatorname{Re} z > 0$ and $z^2 = w$. Then $f_1(w)$ maps the slit plane $\mathbb{C} \setminus (-\infty, 0]$ onto the right half of the z-plane. To specify $f_1(w)$ explicitly, express $w = \rho e^{i\varphi}$ where $-\pi < \varphi < \pi$, and then

$$f_1(w) = \sqrt{\rho} e^{i\varphi/2}.$$

The function f_1 is called the **principal branch** of \sqrt{w} . It is expressed in terms of the argument function as

$$f_1(w) = |w|^{1/2} e^{i(\operatorname{Arg} w)/2}, \qquad w \in \mathbb{C} \setminus (-\infty, 0].$$

The branch $f_2(w)$ is defined similarly except it maps values in the *w*-plane to values on the left half of the *z*-plane. The two slit planes, corresponding to $f_1(w)$ and $f_2(w)$ form the **Riemann surface** of \sqrt{w} .

1.5 The Exponential Function

Definition 1.24. We extend the exponential function to all complex numbers z be defining

$$e^z = e^x \cos y + ie^x \sin y, \qquad z \in \mathbb{C}.$$

Since $e^{iy} = \cos y + i \sin y$, we could write

 $e^z = e^x e^{iy}.$

This identity is simply the polar representation of $w = e^z$:

$$|w| = |e^x|,$$

arg $w = y.$

Since $\cos x$ and $\sin y$ are 2π -periodic, e^z is also 2π -periodic:

$$e^{z+2\pi i} = e^z, \qquad z \in \mathbb{C}.$$

Additional properties of the exponential function

$$\begin{split} e^{z+w} &= e^z e^w, \qquad \qquad z,w \in \mathbb{C}, \\ 1/e^z &= e^{-z}, \qquad \qquad z \in \mathbb{C}. \end{split}$$

1.6 The Logarithm Function

Definition 1.25. For $z \neq 0$, we define $\log z$ to be a multi-valued function

$$\log z = \log |z| + i \arg z,$$

= log |z| + iArg z + 2\pi im, m = 0, \pm 1, \pm 2, \ldots ...

The values of $\log z$ are precisely the complex numbers w such that $e^w = z$.

Definition 1.26. We define the **principle value of** $\log z$ to be

$$\operatorname{Log} z = \log |z| + i\operatorname{Arg} z, \qquad z \neq 0.$$

Thus $\log z$ is a single-valued inverse of e^w with values in the horizontal strip $-\pi < \operatorname{Im} w \leq \pi$. From $\log z$ we can find the other values of $\log z$:

$$\log z = \log z + 2\pi i m, \qquad m = 0, \pm 1, \pm 2, \dots$$

1.7 Power Functions and Phase Factors

Definition 1.27. Let α be an arbitrary complex number. We defined the power function z^{α} to be the multivalued function

$$z^{\alpha} = e^{\alpha \log z}, \qquad z \neq 0.$$

Thus the values of z^a are

$$z^{\alpha} = e^{\alpha [\log |z| + i\operatorname{Arg} z + 2\pi i m]},$$

= $e^{\alpha \operatorname{Log} z} e^{2\pi i \alpha m}, \qquad m = 0, \pm 1, \pm 2, \dots$

If α is not an integer, we cannot define z^{α} on the complex plane such that the function is continuous. We must make a branch cut and consider the continuous branch of z^{α} defined explicitly on the slit plane $\mathbb{C} \setminus [0, \infty)$ by

$$w = r^{\alpha} e^{i\alpha\theta}, \quad \text{for } z = r e^{i\theta}, \quad 0 < \theta < 2\pi$$

For $\theta = 0$, we have $z^{\alpha} = r^{\alpha}$. For $\theta = 2\pi$, we have $z^{\alpha} = r^{\alpha}e^{2\pi i\alpha}$. We call the multiplier $e^{2\pi i\alpha}$ the **phase** factor of z^{α} at z = 0.

Lemma 1.28 (Phase Change Lemma). Let g(z) be a single-valued function that is defined and continuous near z_0 . For any continuously varying branch of $(z - z_0)^{\alpha}$, the function $f(z) = (z - z_0)^{\alpha}g(z)$ is multiplied by the phase factor $e^{2\pi i\alpha}$ when z traverses a complete circle about z_0 in the positive direction.

1.8 Trigonometric and Hyperbolic Functions

Definition 1.29. We extend the definition of $\sin z$ and $\cos z$ to complex numbers by using their exponential forms:

$$\sin z = \frac{e^{iz} + e^{-iz}}{2}, \qquad z \in \mathbb{C},$$
$$\cos z = \frac{e^{iz} - e^{-iz}}{2i}, \qquad z \in \mathbb{C}.$$

These definitions agree with the usual definition when z is real. Evidently, $\cos z$ is still an even function and $\sin z$ is still an odd function,

$$cos(-z) = cos z, \qquad z \in \mathbb{C},$$

$$sin(-z) = -sin z, \qquad z \in \mathbb{C}$$

They are still 2π -periodic:

$$\cos(z+2\pi) = \cos z, \qquad z \in \mathbb{C},$$

$$\sin(z+2\pi) = \sin z, \qquad z \in \mathbb{C}.$$

The addition formulae remain valid,

$$\cos(z+w) = \cos z \cos w - \sin z \sin w, \qquad z \in \mathbb{C},$$

$$\sin(z+w) = \sin z \cos w - \cos z \sin w, \qquad z \in \mathbb{C}.$$

And the following identity still holds true,

$$\cos^2 z + \sin^z = 1, \qquad z \in \mathbb{C}.$$

Definition 1.30. We define the hyperbolic functions in a similar manner.

$$\sinh z = \frac{e^z + e^{-z}}{2}, \qquad z \in \mathbb{C},$$
$$\cosh z = \frac{e^z - e^{-z}}{2}, \qquad z \in \mathbb{C}.$$

Both $\cosh z$ and $\sinh z$ are periodic with period $2\pi i$,

$$\cosh(z + 2\pi i) = \cosh z, \qquad z \in \mathbb{C},$$
 $\sinh(z + 2\pi i) = \sinh z, \qquad z \in \mathbb{C}.$

When viewed as functions of complex variables, the trigonometric and hyperbolic functions exhibit a close relationship. They are obtained from each other by rotating the domain space by $\pi/2$,

$$\cosh(iz) = \cos z,$$
 $\cos(iz) = \cosh z,$
 $\sinh(iz) = i \sin z,$ $\sin(iz) = i \sinh z$

Using these equations and the addition formula for $\sin z$, we obtain the Cartesian representation for $\sin z$,

$$\sin z = \sin x \cosh y + i \cos x \sinh y, \qquad z = x + iy \in \mathbb{C}.$$

Thus,

$$|\sin z|^2 = \sin^2 x \cosh^2 y + \cos^2 x \sinh^2 y.$$

And using $\cos^2 x + \sin^2 x = 1$ and $\cosh^2 y = 1 + \sinh y$, we obtain

$$|\sin z|^2 = \sin^2 x + \sinh^2 y.$$

The other trigonometric and hyperbolic functions are obtained from their usual formulae:

$$\tan z = \frac{\sin z}{\cos z}, \qquad \tanh z = \frac{\sinh z}{\cosh z}, \qquad z \in \mathbb{C}.$$

Definition 1.31. The inverse trigonometric functions are multivalued functions that can be expressed in terms of the logarithm function. Suppose $w = \sin^{-1} z$. Then solving

$$\sin w = \frac{e^{iw} - e^{-iw}}{2i} = z.$$

we obtain

$$\sin^{-1} z = -i \log \left(iz \pm \sqrt{1 - z^2} \right).$$

The other functions can be obtained in a similar manner.

2 Analytic Functions

2.1 Review of Basic Analysis

Definition 2.1. A sequence of complex numbers $\{s_n\}$ converges to s if for any $\epsilon > 0$, there is an integer $N \ge 1$ such that $|s_n - s| < \epsilon$ for all $n \ge N$. If $\{s_n\}$ convergs to s, we write $s_n \to s$ or $\lim s_n = s$.

Definition 2.2. A sequence of complex numbers $\{s_n\}$ is said to be **bounded** if there is some finite number R > 0 such that $|s_n| < R$ for all n.

Theorem 2.3. Suppose $\{s_n\}$ and $\{t_n\}$ are bounded sequences such that $s_n \to s$ and $t_n \to t$, then

- (a) $s_n + t_n \rightarrow s + t$,
- (b) $s_n t_n \to st$,
- (c) $s_n/t_n \to s/t$, provided that $t \neq 0$.

Theorem 2.4. A sequence $\{s_n\}$ of complex numbers converges if and only if the corresponding sequences of real and imaginary parts of the s_n 's converge.

Theorem 2.5. We define a sequence of complex numbers $\{s_n\}$ to be a **Cauchy sequence** if the differences $s_n - s_m$ tend to 0 as n and m tend to ∞ . More formally, a sequence is Cauchy if for any $\epsilon > 0$, there exists an $N \ge 1$ such that $|s_n - s_m| < \epsilon$ if $m, n \ge N$.

Theorem 2.6. A sequence of complex numbers converges if and only if it is a Cauchy sequence.

Definition 2.7. We say that a complex-valued function f(z) has limit L as z tends to z_0 if the valued f(z) are near L whenever z is near z_0 , $z \neq z_0$. More formally, f(z) has limit L as z tends to z_0 if for any $\epsilon > 0$, there is a $\delta > 0$ such that $|f(z) - L| < \epsilon$ whenever $0 < |z - z_0| < \delta$. In this case, we write

$$\lim_{z \to z_0} f(z) = L$$

or $f(z) \to L$ as $z \to z_0$.

Theorem 2.8. The complex-valued function f(z) has limit L as $z \to z_0$ if and only if $f(z_n) \to L$ for any sequence $\{z_n\}$ in the domain of f(z) such that $z_n \to z_0$ and $z_n \to z_0$.

Definition 2.9. If a function has a limit at z_0 , then the function is bounded near z_0 . Further, if $f(z) \to L$ and $g(z) \to M$ as $z \to z_0$, then the following are true as $z \to z_0$:

- (a) $f(z) + g(z) \rightarrow L + M$,
- (b) $f(z)g(z) \to LM$,
- (c) $f(z)/g(z) \to L/M$, provided that $M \neq 0$.

Definition 2.10. We say that f(z) is continuous at z_0 if $f(z) \to f(z_0)$ as $z \to z_0$. A continuous function is a function that is continuous at every point of its domain.

Definition 2.11. A subset U of the complex plane is **open** if whenever $z \in U$, there is a disk centered at z that is contained in U.

Definition 2.12. A subset D of the complex plane is a **domain** if D is open and any two points of D can be connected by a broken line segment within D.

Theorem 2.13. If h(x, y) is continuous differentiable on a domain D such that $\nabla h = 0$ on D, then h is constant.

Definition 2.14. A set is **convex** if whenever two points belong to the set, the straight line segment joining them is contained within the set.

Definition 2.15. A set is **star-shaped with respect to** z_0 if whenever a point belongs to the set, the straight line segment between it and z_0 is contained within the set. Any convex set if star-shaped with respect to each of its points.

Definition 2.16. A star-shaped domain is a domain that is star-shaped with respect to one of its points.

Definition 2.17. A subset E of the complex plane is **closed** if it contains the limit of any convergent subsequence in E.

Definition 2.18. The **boundary** of a set E consists of the points z such that every disk centered at z contains both points in E and not in E. A set is closed if it contains its boundary, and a set is open if it does not include any of its boundary points.

Definition 2.19. A subset of the complex plane is said to be **compact** if it is both closed and bounded.

Theorem 2.20. A continuous real-valued function on a compact set attains a maximum and a minimum.

2.2 Analytic Functions

Definition 2.21. A complex-valued function f(z) is differentiable at z_0 if the difference quotients

$$\frac{f(z) - f(z_0)}{z - z_0}$$

have a limit as $z \to z_0$. The limit is denoted by $f'(z_0)$ or by $\frac{df}{dz}(z_0)$, and we refer to it as the **complex** derivative of f(z) at z_0 . Thus

$$\frac{df}{dz}(z_0) = f'(z_0) = \lim_{z \to z_0} \frac{f(z) - f(z_0)}{z - z_0}.$$

It is often useful to write the difference quotient in the form

$$\frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z}$$

so that $z - z_0$ is replaced by Δz . Then

$$f'(z_0) = \lim_{\Delta z \to 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z}$$

Theorem 2.22. If f(z) is differentiable at z_0 , then f(z) is continuous at z_0 .

Theorem 2.23. The complex derivative satisfies the usual rules of differentiating sums, products and quo-

tients. The rules are

$$(cf)'(z) = cf'(z),$$
 (2.1)

$$(f+g)'(z) = f'(z) + g'(z),$$
(2.2)

$$(fg)'(z) = f(z)g'(z) + f'(z)g(z),$$
(2.3)

$$(f/g)'(z) = \frac{g(z)f'(z) - f(z)g'(z)}{g(z)^2}, \quad g(z) \neq 0.$$
(2.4)

Here we are assuming that f(z) and g(z) are differentiable at z, and that c is any complex constant.

Theorem 2.24 (Chain Rule). Suppose that g(z) is differentiable at z_0 , and suppose that f(w) is differentiable at $w_0 = g(z_0)$. Then the composition $(f \circ g)(z) = f(g(z))$ is differentiable at z_0 and

$$(f \circ g)'(z_0) = f'(g(z_0))g'(z_0)$$

Alternatively, we can write the chain rule as

$$\frac{df}{dz} = \frac{df}{dw}\frac{dw}{dz}.$$

Definition 2.25. A function f(z) is analytic on the open set U if f(z) is (complex) differentiable at each point of U and the complex derivative f'(z) is continuous on U.

2.3 The Cauchy-Riemann Equations

Theorem 2.26. Let f = u + iv be defined on a domain D in the complex plane, where u and v are realvalued. Then f(z) is analytic on D if and only if u(x, y) and v(x, y) have continuous first-order partial derivatives that satisfy

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}, \qquad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}.$$

These equations are called the **Cauchy-Riemann equations** for u and v.

Corollary 2.27. If f(z) is analytic on a domain D and f'(z) = 0 on D, then f(z) is constant.

Corollary 2.28. If f(z) is analytic and real-valued on a domain D, then f(z) is constant.

2.4 Inverse Mappings and the Jacobian

Definition 2.29. Let f = u + iv be analytic on a domain D. We may regard D as a domain in the Euclidean plane \mathbb{R}^2 and f as a mapping from D to \mathbb{R}^2 with components (u(x, y), v(x, y)). The **Jacobian matrix** of this map is

$$J_f = \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix}$$

and its determinant is

$$\det J_f = \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} - \frac{\partial u}{\partial y} \frac{\partial v}{\partial x}$$

Theorem 2.30. If f(z) is analytic, then its Jacobian matrix (as a map of \mathbb{R}^2 to \mathbb{R}^2) has determinant

$$\det J_f = |f'(z)|^2.$$

Theorem 2.31. Suppose f(z) is analytic on a domain $D, z_0 \in D$, and $f'(z_0) \neq 0$. Then there is an disk $U \subset D$ containing z_0 such that f(z) is one-to-one on U, the image V = f(U) of U is open, and the inverse function

$$f^{-1}: V \to U$$

is analytic and satisfies

$$(f^{-1})'(f(z)) = 1/f'(z), \qquad z \in U.$$
 (2.5)

2.5 Harmonic Functions

Definition 2.32. The equation

$$\frac{\partial^2 u}{\partial x_1^2} + \ldots + \frac{\partial^2 u}{\partial x_n^2} = 0$$

is called Laplace's equation. The operator

$$\Delta = \frac{\partial^2}{\partial x_1^2} + \ldots + \frac{\partial}{\partial x_n^2}$$

is called the **Laplacian**. In terms of the operator, Laplace's equation is simply $\Delta u = 0$. Smooth functions $u(x_1, \ldots, x_n)$ that satisfy Laplace's equation are called **harmonic functions**. For complex functions, we will only be concerned about the solutions of the equation

$$\Delta u = \frac{\partial^2 u}{\partial x_1^2} + \frac{\partial^2 u}{\partial x_2^2} = 0.$$

Definition 2.33. We say that a function u(x, y) is **harmonic** if all of its first- and second-order partial derivatives exist and are continuous and satisfy Laplace's equation.

Theorem 2.34. If f = u + iv is analytic, and the functions u and v have continuous second-order partial derivatives, then u and v are harmonic.

Definition 2.35. If u is harmonic on a domain D, and v is a harmonic function such that f = u + iv is analytic, we say that v is a **harmonic conjugate** of u. The harmonic conjugate is unique up to adding a constant.

Theorem 2.36. Let *D* be an open disk, or an open rectangle with sides parallel to the axes, and let u(x, y) be an harmonic function on *D*. Then there is a harmonic function v(x, y) on *D* such that f = u + iv is analytic on *D*. The harmonic conjugate *v* is unique, up to a constant.

2.6 Conformal Mappings

Definition 2.37. Let $\gamma(t) = x(t) + iy(t)$, $0 \le t \le 1$, be a smooth parameterized curve terminating at $z_0 = \gamma(0)$. We refer to

$$\gamma'(0) = \lim_{t \to 0} \frac{\gamma(t) - \gamma(0)}{t} = x'(0) + iy'(0)$$

as the **tangent curve** to the curve γ at z_0 . It is the complex representation of the usual tangent vector. We define the **angle between two curves** at z_0 to be the angle between their tangent vectors at z_0 .

Theorem 2.38. If $\gamma(t)$, $0 \le t \le 1$, is a smooth parameterized curve terminating at $z_0 = \gamma(0)$, and f(z) is analytic, then the tangent to the curve $f(\gamma(t))$ terminating at $f(z_0)$ is

$$(f \circ \gamma)'(0) = f'(z_0)\gamma'(0).$$

Definition 2.39. A function is **conformal** if it preserves angles. More precisely, a smooth complex-valued function g(z) is **conformal at** z_0 if wherenever γ_0 and γ_1 are two curves terminating at z_0 with nonzero tangents, then the curves $g \circ \gamma_0$ and $g \circ \gamma_1$ have nonzero tangents at $g(z_0)$ and the angle from $(g \circ \gamma_0)'(z_0)$ to $(g \circ \gamma_1)'(z_0)$ is the same as the angle from $\gamma'_0(z_0)$ to $\gamma'_1(z_0)$.

Definition 2.40. A conformal mapping of one domain D onto another V is a continuously differentiable function that is conformal at each point of D and that maps D one-to-one onto V.

Theorem 2.41. If f(z) is analytic at z_0 and $f'(z_0) \neq 0$, then f(z) is conformal at z_0 .

2.7 Fractional Linear Transformations

Definition 2.42. A fractional linear transformation is a function of the form

$$w = f(z) = \frac{az+b}{cz+d},$$

where a, b, c, d are complex constants satisfying $ad - bc \neq 0$. The transformations are also called **Möbius** transformations. Special cases of fractional linear transformations include translations $z \to z + b$, dilations $z \to az$, and the inversion $z \to 1/z$. A function of the form f(z) = az + b, where $a \neq 0$, is also called an affine transformation.

Theorem 2.43. Given three distinct points z_0, z_1, z_2 in the extended complex plane, and given any three distinct values w_0, w_1, w_2 in the extended complex plane, there is a unique fractional linear transformation w = w(z) such that $w(z_0) = w_0, w(z_1) = w_1$, and $w(z_2) = z_2$.

Theorem 2.44. Every fractional linear transformations is a composition of dilations, translations, and inversion.

Theorem 2.45. A fractional linear transformation maps circles in the extended complex plane to circles.

3 Line Integrals and Harmonic Functions

3.1 Line Integrals and Green's Theorem

Definition 3.1. A path in the plane from A to B is a continuous function $t \mapsto \gamma(t)$ on some parameter interval $a \leq t \leq b$. such that $\gamma(a) = A$ and $\gamma(b) = B$. The path is **simple** if $\gamma(s) \neq \gamma(t)$ when $s \neq t$. The path is **closed** if it starts and ends at the same point, that is, $\gamma(a) = \gamma(b)$. A **simple closed path** is a closed path γ such that $\gamma(s) \neq \gamma(t)$ for $a \leq s < t < b$.

Lemma 3.2. If $\gamma(t), a \leq t \leq b$, is a path from A to B, and if $\phi(s), \alpha \leq s \leq \beta$, is a strictly increasing continuous function satisfying $\phi(\alpha) = a$ and $\phi(\beta) = b$, then the composition $\gamma(\phi(s)), \alpha \leq s \leq \beta$ is also a path form A to B.

Definition 3.3. The trace of a path γ is its image $\gamma([a, b])$, which is a subset of the plane.

Definition 3.4. A smooth path is a path that can be represented in the form $\gamma(t) = (x(t), y(t)), a \le t \le b$ where the functions x(t) and y(t) are smooth. A **piecewise smooth path** is a concatenation of smooth paths. A **curve** is a (usually) smooth or piecewise smooth path. **Definition 3.5.** Let γ be a smooth path on the complex plane and let P(x, y) and Q(x, y) be continuous complex-valued functions. We consider successive points along the path and form the sum

$$\sum P(x_j, y_j)(x_{j+1} - x_j) + \sum Q(x_j, y_j)(y_{j+1} - y_j).$$
(3.1)

If these sums have a limit as the distance between the succesive point tend to 0, we define the limit to be the **line integral** of P dx + Q dy along γ and denote it by

$$\int_{\gamma} P \, dx + Q \, dy. \tag{3.2}$$

Lemma 3.6. Suppose that path $\gamma(t) = (x(t), y(t)), a \le t \le b$ is continuously differentiable, that is, the parameter functions x(t) and y(t) are continuously differentiable. Then (3.2) can be written as

$$\int_{\gamma} P \, dx + Q \, dy = \int_{a}^{b} P(x(t), y(t)) \frac{dx}{dt} \, dt + \int_{a}^{b} Q(x(t), y(t)) \frac{dy}{dt} \, dt.$$
(3.3)

Thus to compute the line integral, we parameterize the curve by $t \to (x(t), y(t))$ and calculate dx/dt and dy/dt and plug these into the definite integral in (3.3).

Definition 3.7. A domain D has **piecewise smooth boundary** if the boundary of D can be decomposed into a finite number of smooth curves meeting only at the endpoints. We denote the boundary of D by ∂D . For the purposes of integration, the **orientation of** D is chosen so that D lies on the left of a curve in ∂D as we traverse the boundary curve in the positive direction, as the parameter value increases.

Theorem 3.8 (Green's Theorem). Let D be a bounded domain in the plane whose boundary ∂D consists of a finite number of disjoint piecewise smooth closed curves. Let P and Q be continuously differentiable functions on $D \cup \partial D$. Then

$$\int_{\partial D} P \, dx + Q \, dy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \, dx \, dy. \tag{3.4}$$

3.2 Independence of Path

Definition 3.9. If h(x, y) is a continuously differentiable complex-valued function, we define the **differential** dh of h by

$$dh = \frac{\partial h}{\partial x} \, dx + \frac{\partial h}{\partial y} \, dy$$

We say that a differential P dx + Q dy is **exact** if P dx + Q dy = dh for some function h. The function h plays the role of the antiderivative from single-variable calculus.

Theorem 3.10 (Fundamental Theorem of Calculus, Part I). If γ is a piecewise smooth curve from A to B, and if h(x, y) is continuously differentiable on γ , then

$$\int_{\gamma} dh = h(B) - h(A). \tag{3.5}$$

Definition 3.11. Let P and Q be continuous complex-valued functions on a domain D. We say that a line integral $\int P \, dx + Q \, dy$ is **independent of path** in D if for any two points A and B in D, the integrals $\int_{\gamma} P \, dx + Q \, dy$ are the same for any path γ between A and B. This is equivalent to saying $\int_{\gamma} P \, dx + Q \, dy = 0$ for any closed path in D.

Lemma 3.12. Let P and Q be continuous complex-valued functions on a domain D. Then $\int P dx + Q dy$ is independent of path in D if and only if P dx + Q dy is exact, that is, there is a continuously differentiable function h(x, y) such that dh = P dx + Q dy. Moreover, the function h is unique, up to adding a constant.

Lemma 3.13. We say that a differential is closed on D if

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}.\tag{3.6}$$

This is precisely the condition that the integrand in Green's theorem is zero. Thus Green's theorem implies that if P dx + Q dy is closed on D, then $\int_{\partial U} P dx + Q dy = 0$ for any bounded domain D with piecewise smooth boundary such that U is contained in D.

Lemma 3.14. Exact differentials are closed.

Theorem 3.15 (Fundamental Theorem of Calculus, Part II). Let P and Q be continuously differentiable complex-valued functions on a domain D. If D is a star-shaped domain and the differential P dx + Q dyis closed on D, then P dx + Q dy is exact on D.

Remark. In general, for a differential P dx + Q dy,

independent of path \iff exact \implies closed.

For star-shaped domains, it is additionally true that

independent of path \iff exact \iff closed.

Theorem 3.16. Let *D* be a domain, and let $\gamma_0(t)$ and $\gamma_1(t)$, $a \leq t \leq b$, be two paths in *D* from *A* to *B*. Suppose γ_0 can be continually deformed to γ_1 , in the sense that for $0 \leq s \leq 1$ there are paths $\gamma_s(t)$, $a \leq t \leq b$, from *A* to *B* such that $\gamma_s(t)$ depends continuously on *s* and *t* for $0 \leq s \leq 1$, $a \leq t \leq b$. Then

$$\int_{\gamma_0} P \, dx + Q \, dy = \int_{\gamma_1} P \, dx + Q \, dy$$

for any closed differential P dx + Q dy on D.

Theorem 3.17. Let *D* be a domain, and let $\gamma_0(t)$ and $\gamma_1(t)$, $a \le t \le b$, be two closed paths in *D*. Suppose γ_0 can be continually deformed to γ_1 , in the sense that for $0 \le s \le 1$ there are paths $\gamma_s(t)$, $a \le t \le b$, such that $\gamma_s(t)$ depends continuously on *s* and *t* for $0 \le s \le 1$, $a \le t \le b$. Then

$$\int_{\gamma_0} P \, dx + Q \, dy = \int_{\gamma_1} P \, dx + Q \, dy$$

for any closed differential P dx + Q dy on D.

3.3 Harmonic Conjugates

Lemma 3.18. If u(x, y) is harmonic, then the differential

$$-\frac{\partial u}{\partial y}\,dy + \frac{\partial v}{\partial x}\,dy\tag{3.7}$$

is closed.

Theorem 3.19. Any harmonic function u(x, y) on a star-shaped domain D (as a disk or rectangle) has a harmonic conjugate function v(x, y) on D.

3.4 The Mean Value Property

Definition 3.20. Let h(z) be a continuous real-valued function on a domain D. Let $z_0 \in D$, and suppose D contains the disk $\{|z - z_0| < \rho\}$. We define the **average value** of h(z) on the circle $\{|z - z_0| = r\}$ to be

$$A(r) = \int_0^{2\pi} h(z_0 + re^{i\theta}) \, \frac{d\theta}{2\pi}, \qquad 0 < r < \rho.$$

Theorem 3.21. If u(z) is a harmonic function on a domain D, and if the disk $\{|z - z_0| < \rho\}$ is contained in D, then

$$u(z_0) = \int_0^{2\pi} u(z_0 + re^{i\theta}) \frac{d\theta}{2\pi}, \qquad 0 < r < \rho.$$
(3.8)

In other words, the average value of a harmonic function on the boundary circle of any disk contained in D is its value at the center of the disk.

Definition 3.22. We say that a continuous function h(z) on a domain D has the **mean value property** if for every point $z_0 \in D$, $h(z_0)$ is the average of its value over any small circle centered at z_0 . More formally, for any $z_0 \in D$, there is an $\epsilon > 0$ such that

$$h(z_0) = \int_0^{2\pi} h(z_0 + re^{i\theta}) \frac{d\theta}{2\pi}, \qquad 0 < r < \epsilon.$$

Harmonic functions satisfy the mean value property. The converse is also true: continuous functions that satisfy the mean value property are harmonic functions (Section 10).

3.5 The Maximum Principle

Theorem 3.23 (Strict Maximum Principle, Real Version). Let u(z) be a real-valued harmonic function on a domain D such that $u(z) \leq M$ for all $z \in D$. If $u(z_0) = M$ for some $z_0 \in D$, then u(z) = M for all $z \in D$.

Theorem 3.24 (Strict Maximum Principle, Complex Version). Let h(z) be a complex-valued harmonic function on a domain D such that $|h(z)| \leq M$ for all $z \in D$. If $|h(z_0)| = M$ for some $z_0 \in D$, then h(z) is constant on D.

Theorem 3.25 (Maximum Principle). Let h(z) be a complex-valued harmonic function on a bounded domain D such that h(z) extends continuously to the boundary ∂D of D. If $|h(z)| \leq M$ for all $z \in \partial D$, then $|h(z)| \leq M$ for all $z \in D$.

3.6 Applications to Fluid Dynamics

This section contains no definitions or theorems.

3.7 Other Applications to Physics

This section contains no definitions or theorems.

4 Complex Integration and Analyticity

4.1 Complex Line Integrals

Definition 4.1. For complex analysis, it is convenient to define dz = dx + i dy. According, to this notation, if h(z) is a complex-valued function on a curve γ , then

$$\int_{\gamma} h(z) \, dz = \int_{\gamma} h(z) \, dx + i \int_{\gamma} h(z) \, dy.$$

Additionally, we define the infinitesimal arc length ds by |dz|:

$$|dz| = ds = \sqrt{(dx)^2 + (dy)^2}.$$

This means that if a curve γ is parameterized by z(t) = x(t) + iy(t), then

$$\int_{\gamma} h(z) \left| dz \right| = \int_{\gamma} h(z) \, ds = \int_{a}^{b} h(z(t)) \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dy}\right)^{2}}.$$

In particular, the length of γ is

$$L = \int_{\gamma} |dz| = \int_{a}^{b} \sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dy}\right)^{2}}.$$

Theorem 4.2. Suppose γ is a piecewise smooth curve. If h(z) is a continuous function on γ , then

$$\left| \int_{\gamma} h(z) \, dz \right| \le \int_{\gamma} |h(z)| \, |dz|. \tag{4.1}$$

Further if γ has length L and $|h(z)| \leq M$ on γ , then

$$\left| \int_{\gamma} h(z) \, dz \right| \le ML. \tag{4.2}$$

The estimate (4.1) is the triangle inequality for integrals. The estimate (4.2) is called the **ML-estimate**.

4.2 Fundamental Theorem of Calculus for Analytic Functions

Definition 4.3. Let f(z) be a continuous function on a domain D. A function F(z) on D is a (complex) primitive for f(z) if F(z) is analytic and F'(z) = f(z).

Theorem 4.4 (Part I). If f(z) is continuous on a domain D, and if F(z) is a primitive for f(z), then

$$\int_{A}^{B} f(z) \, dz = F(B) - F(A)$$

where the integral can be taken over any path in D from A to B.

Theorem 4.5 (Part II). Let D be a star-shaped domain and let f(z) be analytic on D. Then f(z) has a primitive on D, and the primitive is unique up to adding a constant. A primitive for f is given explicitly by

$$F(z) = \int_{z_0}^{z} f(\zeta) \, d\zeta, \qquad z \in D,$$

where z_0 is any fixed point of D, and where the integral can be taken along any path in D from z_0 to z.

4.3 Cauchy's Theorem

Theorem 4.6. A continuously differentiable function f(z) on D is analytic if and only if the differential f(z) dz is closed.

Theorem 4.7 (Cauchy's Theorem). Let D be a bounded domain with piecewise smooth boundary. If f(z) is an analytic function on D that extends smoothly to ∂D , then

$$\int_{\partial D} f(z) \, dz = 0$$

4.4 Cauchy Integral Formula

Theorem 4.8 (Cauchy Integral Formula). Let D be a bounded domain with piecewise smooth boundary. If f(z) is analytic on D, and f(z) extends smoothly to the boundary of D, then

$$f(z) = \frac{1}{2\pi i} \int_{\partial D} \frac{f(w)}{w - z} \, dw, \qquad z \in D.$$

Theorem 4.9. Let D be a bounded domain with piecewise smooth boundary. If f(z) is analytic on D, and f(z) extends smoothly to the boundary of D, then f(z) has complex derivatives of all orders on D, which are given by

$$f^{(m)}(z) = \frac{m!}{2\pi i} \int_{\partial D} \frac{f(w)}{(w-z)^{m+1}} \, dw \qquad z \in D, m \ge 0.$$

Corollary 4.10. If f(z) is analytic on a domain D, then f(z) is infinitely differentiable, and the successive complex derivatives $f'(z), f''(z), \ldots$ are all analytic on D.

4.5 Liouville's Theorem

Theorem 4.11 (Cauchy estimates). Suppose f(z) is analytic for $|z-z_0| \le \rho$. If $|f(z)| \le M$ for $|z-z_0| = \rho$, then

$$\left|f^{(m)}(z_0)\right| \le \frac{m!}{\rho^m} M, \qquad m \ge 0.$$

Definition 4.12. We define an **entire function** to be a function that is analytic on the entire complex plane.

Theorem 4.13 (Liouville's Theorem). A bounded entire function is constant.

4.6 Morera's Theorem

Theorem 4.14 (Morera's Theorem). Let f(z) be a continuous function on a domain D. If $\int_{\partial R} f(z) dz = 0$ for every closed rectangle R in D with sides parallel to the coordinate axis, then f(z) is analytic on D.

Theorem 4.15. Suppose that h(t, z) is a continuous, complex-valued function, defined for $a \le t \le b$ and $z \in D$. If for each fixed t, h(t, z) is an analytic function of $z \in D$, then

$$H(z) = \int_{a}^{b} h(t, z) \, dz, \qquad z \in D,$$

is analytic on D.

Theorem 4.16. Suppose that h(z) is a continuous function on a domain D that is analytic on $D \setminus \mathbb{R}$, that is, on the part of D not lying on the real axis. Then f(z) is analytic on D.

4.7 Goursat's Theorem

Theorem 4.17 (Goursat's Theorem). If f(z) is a complex-valued function on a domain D such

$$f'(z_0) = \lim_{z \to z_0} \frac{f(z) - f(z_0)}{z - z_0}$$

exists at each point z_0 of D, then f(z) is analytic on D.

4.8 Complex Notation and Pompeiu's Formula

Definition 4.18. Many results in complex analysis can be expressed in terms of the first-order differential operators

$$\frac{\partial}{\partial z} = \frac{1}{2} \left[\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right], \qquad \frac{\partial}{\partial \overline{z}} = \frac{1}{2} \left[\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right].$$

Thus, we can think of $\partial f/\partial z$ as an average of the derivatives of f(z) in the x and in the *iy* directions. When deriving the Cauchy-Riemann equations, we derived two equations for f'(z),

$$f'(z) = \frac{\partial f}{\partial x}$$
 and $f'(z) = -i\frac{\partial f}{\partial y}$.

Taking the average of these expressions, we get

$$f'(z) = \frac{\partial f}{\partial z},\tag{4.3}$$

assuming that f(z) is analytic. If we let f = u + iv, then

$$\frac{\partial f}{\partial \overline{z}} = \frac{1}{2} \left[\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right] + \frac{i}{2} \left[\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right]$$

Therefore, we obtain the equation

$$\frac{\partial f}{\partial \overline{z}} = 0 \tag{4.4}$$

is equivalent to the Cauchy-Riemann equations. This equation is called the **complex form of the Cauchy-Riemann equations**.

Theorem 4.19. Let f(z) be a continuously differentiable function on a domain D. Then f(z) is analytic if and only if f(z) satisfies that complex form (4.4) of the Cauchy-Riemann equations. If f(z) is analytic, then the derivative of f(z) is given by (4.3).

Theorem 4.20. Let f(z) be a continuously differentiable function on a domain D. Suppose that the gradient of f(z) does not vanish at any point on D, and that f(z) is conformal. Then f(z) is analytic on D, and $f'(z) \neq 0$ on D.

Theorem 4.21. If D is a bounded domain in the complex plane with piecewise smooth boundary, and if g(z) is a smooth function on $D \cup \partial D$, then

$$\int_{\partial D} g(z) \, dz = 2i \iint_{D} \frac{\partial g}{\partial \overline{z}} \, dx \, dy$$

Theorem 4.22 (Pompeiu's Formula). Suppose D is a bounded domain in the complex plane with piecewise smooth boundary. If g(z) is a smooth complex-valued function on $D \cup \partial D$, then

$$g(w) = \frac{1}{2\pi i} \int_{\partial D} \frac{g(z)}{z - w} dz - \frac{1}{\pi} \iint_{D} \frac{\partial g}{\partial \overline{z}} \frac{1}{z - w} dx dy, \qquad w \in D.$$

$$(4.5)$$

The formula (4.5) is also known as the **Cauchy-Green formula**.

5 Power Series

5.1 Infinite Series

Definition 5.1. A series $\sum_{k=0}^{\infty} a_k$ of complex numbers is said to **converge** to *S* if sequence of partial sums $S_k = a_0 + \ldots + a_k$ converges to *S*. We denote the sum *S* by $\sum_{k=0}^{\infty} a_k$ or $\sum a_k$. Any statement about series is just a statement about sequences. Thus if $\sum a_k = A$ and $\sum b_k = B$, then $\sum (a_k + b_k) = A + B$ and $\sum ca_k = cA$.

Theorem 5.2 (Comparison Test). If $0 \le a_k \le r_k$, and if $\sum r_k$ converges, then $\sum a_k$ converges and $\sum a_k \le \sum r_k$.

Theorem 5.3. If $\sum a_k$ converges, then $a_k \to 0$ as $k \to \infty$.

Definition 5.4. The series $\sum a_k$ is said to converge absolutely if $\sum |a_k|$ converges.

Theorem 5.5. If $\sum a_k$ converges absolutely, then $\sum a_k$ converges, and

$$\left|\sum_{k=0}^{\infty} a_k\right| \le \sum_{k=0}^{\infty} |a_k|.$$

5.2 Sequences and Series of Functions

Definition 5.6. Let $\{f_j\}$ be a sequence of complex-valued functions defined on some set E. We set that the sequence $\{f_j\}$ converges pointwise on E if for each point $x \in E$, the sequence of complex numbers $\{f_j(x)\}$ converges. The limit f(x) of $\{f_j(x)\}$ is then a complex-valued function on E.

Definition 5.7. We set that the sequence $\{f_j\}$ of functions on E converges uniformly to f on E if $|f_j(x) - f(x)| \le \epsilon_j$ for all $x \in E$, where $\epsilon_j \to 0$ as $j \to \infty$. We can think of ϵ_j as the worst-case estimator of the difference $|f_j(x) - f(x)|$, that is $\epsilon_j = \sup |f_j(x) - f(x)|$. Note that if $\{f_j\}$ converges uniformly to f on E, then $\{f_j\}$ converges pointwise to f on E.

Theorem 5.8. Let $\{f_j\}$ be a sequence of complex-valued functions defined on a subset E of the complex plane. If each f_j is continuous on E and $\{f_j\}$ converges uniformly to f on E, then f is continuous on E.

Theorem 5.9. Let γ be a piecewise smooth curve in the complex plane. If $\{f_j\}$ is a sequence of complexvalued functions on γ , and $\{f_j\}$ converges uniformly to f on γ , then $\int_{\gamma} f_j(z) dz$ converges to $\int_{\gamma} f(z) dz$.

Definition 5.10. We say that series **converges pointwise** on E if the sequence of partial sums converges pointwise on E, and the series **converges uniformly** on E if the sequence of partial sums converges uniformly on E.

Theorem 5.11 (Weierstrass *M*-**Test).** Suppose $M_k \ge 0$ and $\sum M_k$ converges. If $g_k(z)$ are complexvalued functions on a set *E* such that $|g_k(x)| \le M_k$ for all $x \in E$, then $\sum g_k(x)$ converges uniformly on *E*.

Theorem 5.12. If $\{f_k(z)\}$ is a sequence of analytic functions on a domain D that converges uniformly to f(z) on D, then f(z) is analytic on D.

Theorem 5.13. Suppose that $f_k(z)$ is analytic for $|z - z_0| \leq R$, and suppose that the sequence $\{f_k(z)\}$

converges uniformly to f(z) for $|z - z_0| \le R$. Then for each r < R and for each $m \ge 1$, the sequence of mth derivatives $\{f_k^{(m)}(z)\}$ converges uniformly to $f^{(m)}(z)$ for $|z - z_0| \le r$.

Definition 5.14. We say that a sequence $\{f_k(z)\}$ of analytic functions on a domain D converges normally to the analytic function f(z) on D if it converges uniformly to f(z) on each closed disk contained in D.

Theorem 5.15. Suppose that $\{f_k(z)\}$ is a sequence of analytic functions on a domain D that converges normally on D to the analytic functions f(z). Then for each $m \ge 1$, the sequence of mth derivatives $\{f_k^{(m)}(z)\}$ converges normally to $f^{(m)}(z)$ on D.

5.3 Power Series

Definition 5.16. A power series (centered at z_0) is a series of the form $\sum_{k=0}^{\infty} a_k (z-z_0)^k$.

Theorem 5.17. Let $\sum a_k z^k$ be a power series. Then there is an R, $0 \le R \le \pm \infty$, such that $\sum a_k z^k$ converges absolutely if |z| < R, and $\sum a_k z^k$ does not converge if |z| < R. For each fixed r satisfying r < R, the series $\sum a_k z^k$ converges uniformly for $|z| \le r$.

Definition 5.18. We call R the radius of convergence of the series $\sum a_k z^k$. The radius of convergence depends only on the tail of the series.

Theorem 5.19. Suppose $\sum a_k z^k$ is a power series with radius of convergence R > 0. Then the function

$$f(z) = \sum_{k=0}^{\infty} a_k z^k, \qquad |z| < R$$

is analytic. The derivatives of f(z) are obtained by differentiating the series term by term,

$$f'(z) = \sum_{k=1} k a_k z^{k-1}, \qquad f''(z) = \sum_{k=2}^{\infty} k(k-1)a_k z^{k-2}, \qquad |z| < R,$$

and similarly for the higher-order derivatives. The coefficients of the series are given by

$$a_k = \frac{1}{k!} f^{(k)}(0), \qquad k \ge 0$$

Theorem 5.20 (Ratio Test). If $|a_k/a_{k+1}|$ has a limit as $k \to \infty$, either finite or $+\infty$, then the limit is the radius of convergence R of $\sum a_k z^k$,

$$R = \lim_{k \to \infty} \left| \frac{a_k}{a_{k+1}} \right|.$$

Theorem 5.21 (Root Test). If $\sqrt[k]{|a_k|}$ has a limit as $k \to \infty$, either finite or $+\infty$, then the radius of convergence R of $\sum a_k z^k$ is given by

$$R = \frac{1}{\lim \sqrt[k]{|a_k|}}.$$
(5.1)

Definition 5.22. There is a more general form of the formula (5.1) called the **Cauchy-Hadamard formula**, that gives the radius of convergence for any power series in terms of the lim sup,

$$R = \frac{1}{\limsup \sqrt[k]{|a_k|}}$$

5.4 Power Series Expansion of an Analytic Function

Theorem 5.23. Suppose that f(z) is analytic for $|z - z_0| < \rho$. Then f(z) is represented by the power series

$$f(z) = \sum_{k=0}^{\infty} a_k (z - z_0)^k, \qquad |z - z_0| < \rho,$$

where

$$a_k = \frac{f^{(k)}(z_0)}{k!} \qquad k \ge 0$$

and where the power series has radius of convergence $R \ge \rho$. For any fixed r, $0 < r < \rho$, we have

$$a_k = \frac{1}{2\pi i} \oint_{|\zeta - z_0| = r} \frac{f(\zeta)}{(\zeta - z_0)^{k+1}} \, d\zeta, \qquad k \ge 0.$$

Further, if $|f(z)| \leq M$ for $|z - z_0| = r$, then

$$|a_k| \le \frac{M}{r^k}, \qquad k \ge 0$$

Corollary 5.24. Suppose that f(z) and g(z) are analytic on $|z - z_0| < r$. If $f^{(k)}(z_0) = g^{(k)}(z_0)$ for $k \ge 0$, then f(z) = g(z) for $|z - z_0| < r$.

Corollary 5.25. Suppose that f(z) is analytic at z_0 with power series expansion $f(z) = \sum a_k (z - z_0)^k$ centered at z_0 . Then the radius of convergence of the power series is the largest number R such that f(z) extends to be analytic on the disk $\{|z - z_0| < R\}$.

5.5 Power Series Expansions at Infinity

Definition 5.26. We say a function f(z) is **analytic at** $z = \infty$ if the function g(w) = f(1/w) is analytic at w = 0. If f(z) is analytic at ∞ , then g(w) = f(1/w) has the power series expansion centered at w = 0,

$$g(w) = \sum_{k=0}^{\infty} b_k w^k = b_0 + b_1 w + b_2 w^2 + b_3 w^3 + \cdots, \qquad |w| < \rho.$$

Thus f(z) is represented by a convergent series expansion in descending powers of z,

$$f(z) = \sum_{k=0}^{\infty} \frac{b_k}{z^k} = b_0 + \frac{b_1}{z} + \frac{b_2}{z^2} + \frac{b_3}{z^3} + \cdots, \qquad |z| > \frac{1}{\rho}.$$

This series converges absolutely for $|z| > 1/\rho$, and for any $r > 1/\rho$ it converges uniformly for $|z| \ge r$.

A formula for the coefficients can be obtained by multiplying the series z^m and integrating term by term around the circle |z| = r. We have

$$\int_{|z|=r} f(z)z^m \, dz = \int_{|z|=r} \left(\sum b_k z^{-k}\right) z^m \, dz = \sum b_k \int_{|z|=r} z^{m-k} \, dz = 2\pi i b_{m+1}.$$

Thus the coefficient b_k of $1/z^k$ is given by

$$b_k = \frac{1}{2\pi i} \int_{|z|=r} f(z) z^{k-1} dz, \qquad k \ge 0.$$

5.6 Manipulation of Power Series

Remark. Let f(z) and g(z) be analytic at 0, with power series representation

$$f(z) = \sum_{k=0}^{\infty} a_k z^k, \qquad g(z) = \sum_{k=0}^{\infty} b_k z^k,$$

and let c be a complex constant. The power series of the sum f(z) + g(z) is obtained by simply adding coefficients,

$$f(z) + g(z) = \sum_{k=0}^{\infty} (a_k + b_k) z^k$$

The power series of cf(z) is obtained by multiplying coefficients by c,

$$cf(z) = \sum_{k=0}^{\infty} ca_k z^k.$$

The product f(z)g(z) is given by

$$f(z)g(z) = \sum_{k=0}^{\infty} c_k z^k,$$

where the coefficients c_k are given by

$$c_k = a_k b_0 + a_{k-1} b_1 + \dots + a_1 b_{k-1} + a_0 b_k, \qquad k \ge 0.$$

If g(0) = 1, then the reciprocal 1/g(z) can be computed. The power series expansion of g(z) has the form

$$g(z) = 1 + \sum_{k=1}^{\infty} b_k z^k = 1 + b_1 z + b_2 z^2 + \cdots$$

If z is near 0, the sum $\sum_{k=1}^{\infty} b_k z^k$ is small, and we can expand 1/g(z) in a geometric series

$$\frac{1}{g(z)} = \frac{1}{1 + \sum_{k=1}^{\infty} b_k z^k} = 1 - \left(\sum_{k=1}^{\infty} b_k z^k\right) + \left(\sum_{k=1}^{\infty} b_k z^k\right)^2 - \left(\sum_{k=1}^{\infty} b_k z^k\right)^3 + \cdots$$

5.7 The Zeros of an Analytic Function

Definition 5.27. Let f(z) be analytic at z_0 and suppose $f(z_0) = 0$. We say that f(z) has a zero of order N at z_0 if

$$f(z_0) = f'(z_0) = \dots + f^{(N-1)}(z_0) = 0$$

If we write f(z) using its power series representation,

$$f(z_0) = a_N(z - z_0)^N + a_{N+1}(z - z_0)^{N+1} + \dots$$

then we can factor out $(z - z_0)^N$ and write

$$f(z_0) = (z - z_0)^N h(z), (5.2)$$

where h(z) is analytic at z_0 and $h(z_0) = a_N \neq 0$. Conversely, if there is a factorization (5.2) where h(z) is analytic at z_0 and $h(z_0) \neq 0$, then the leading term in the power series for f(z) is $h(z_0)(z-z_0)^N$, and f(z)has a zero of order N at z_0 . A zero of order one is called a **simple zero**, and a zero of order two is called a **double zero**. **Definition 5.28.** We say that a point $z_0 \in E$ is an **isolated point** of the set E if there is $\rho > 0$ such that $|z - z_0| \ge \rho$ for all points in E other than z_0 . In other words, z_0 is an isolated point of E if z_0 is a positive distance from $E \setminus \{z_0\}$. If E is a set such that every point of E is an isolated point of E, we say that the points of E are isolated.

Theorem 5.29. If D is a domain, and f(z) is an analytic function on D that is not identically zero, then the zeros of f(z) are isolated.

Theorem 5.30 (Uniqueness Principle). If f(z) and g(z) are analytic on a domain D, and if f(z) = g(z) for all z belonging to a set that has a nonisolated point, then f(z) = g(z) for all $z \in D$.

Theorem 5.31 (Principle of Permanence of Functional Equations). Let D be a domain, and let E be a subset of D that has a nonisolated point. Let F(z, w) be a function defined for $z, w \in D$ such that F(z, w) is analytic in z for each fixed $w \in D$ and analytic in w for each fixed $z \in D$. If F(z, w) = 0 whenever z and w both belong to E, then F(z, w) = 0 for all $z, w \in D$.

5.8 Analytic Continuation

Lemma 5.32. Suppose D is a disk, f(z) is analytic on D, and $R(z_1)$ is the radius of convergence of the power series expansion of f(z) about a point $z_1 \in D$. Then

$$|R(z_1) - R(z_2)| \le |z_1 - z_2|, \qquad z_1, z_2 \in D.$$

Definition 5.33. Suppose $\sum a_n(z-z_0)^n$ represents a function f(z) near z_0 . Let $\gamma(t), a \leq t \leq b$, be a path starting at $z_0 = \gamma(a)$. We say that f(z) is **analytically continuable along** γ if for each t there is a convergent power series

$$f_t(z) = \sum_{n=0}^{\infty} a_n(t)(z - \gamma(t))^n, \qquad |z - \gamma(t)| < r(t),$$
(5.3)

such that $f_a(z)$ is the power series representing f(z) at z_0 , and such that when s is near t, then $f_s(z) = f_t(z)$ for z in the intersection of disks of convergence. By the uniqueness principle, the series $f_t(z)$ determines uniquely each of the series $f_s(z)$ for s near t. It follows that the series $f_b(z)$ is uniquely determined by $f_a(z)$.

We refer to $f_b(z)$ as the **analytic continuation** of f(z) along γ , where we regard $f_b(z)$ either as a power series or as an analytic function defined near $\gamma(b)$. Since the coefficients $a_n(t)$ (5.3) are given by $a_n(s) = f_t^{(m)}(\gamma(s))/m!$ for s near t, the coefficients depend continuously on the parameter t.

Theorem 5.34. Suppose f(z) can be continued analytically along the path $\gamma(t)$, $a \leq t \leq b$. Then the analytic continuation is unique. Further, for each $n \geq 0$ the coefficient $a_n(t)$ of the series (5.3) depends continuously on t, and the radius of convergence of the series (5.3) depends continuously on t.

Lemma 5.35. Suppose f(z) is analytic at z_0 , and suppose that $\gamma(t), a \leq t \leq b$, is a path from $z_0 = \gamma(a)$ to $z_1 = \gamma(b)$ along which f(z) has analytic continuation $f_t(z)$. Then the radius of convergence R(t) of the power series (5.3) varies continuously with t, and there is a $\delta > 0$ such that $R(t) \geq \delta$ for all $t, a \leq t \leq b$.

Lemma 5.36. Let f, γ , and δ be as above. If $\sigma(t), a \leq t \leq b$ is another path from z_0 to z_1 such that $|\sigma(t) - \gamma(t)| < \delta$ for $a \leq t \leq b$, then there is an analytic continuation $g_t(z)$ of $f_t(z)$ along σ , and the terminal series $g_b(z)$ centered at $\sigma(b) = z_1$ coincides with $f_b(z)$.

Theorem 5.37 (Monodromy Theorem). Let f(z) be analytic at z_0 . Let $\gamma_0(t)$ and $\gamma_1(t)$, $a \le t \le b$, be two paths from z_0 to z_1 along which f(z) can be continued analytically. Suppose $\gamma_0(t)$ can be deformed

continuously to $\gamma_1(t)$ by paths $\gamma_s(t)$, $0 \le s \le 1$, from z_0 to z_1 such that f(z) can be continued analytically along each path γ_s . Then the analytic continuations of f(z) along γ_0 and along γ_1 coincide at z_1 .

6 Laurent Series and Isolated Singularities

6.1 Laurent Decomposition

Theorem 6.1 (Laurent Decomposition). Suppose $0 \le \rho < \sigma \le +\infty$, and suppose f(z) is analytic for $\rho < |z - z_0| < \sigma$. Then f(z) can be decomposed as a sum

$$f(z) = f_0(z) + f_1(z), (6.1)$$

where $f_0(z)$ is analytic for $|z - z_0| < \sigma$, and $f_1(z)$ is analytic for $|z - z_0| > \rho$ and at ∞ . If we normalize the decomposition so that $f_1(\infty) = 0$, then the decomposition is unique.

Remark. To find such a decomposition (6.1), we apply Cauchy integral representation theorem on an annulus, as follows. Choose r and s such that $\rho < r < s < \sigma$. The Cauchy integral formula for an annulus yields

$$f(z) = \frac{1}{2\pi i} \int_{|\zeta - z_0| = s} \frac{f(\zeta)}{\zeta - z} d\zeta - \frac{1}{2\pi i} \int_{|\zeta - z_0| = r} \frac{f(\zeta)}{\zeta - z} d\zeta,$$

which is valid for $r < |z - z_0| < s$. The function

$$f_0(z) = \frac{1}{2\pi i} \int_{|\zeta - z_0| = s} \frac{f(\zeta)}{\zeta - z} \, d\zeta, \qquad |z - z_0| < s,$$

is analytic for $|z - z_0| < s$, and the function

$$f_1(z) = -\frac{1}{2\pi i} \int_{|\zeta - z_0| = r} \frac{f(\zeta)}{\zeta - z} d\zeta, \qquad |z - z_0| > r,$$

is analytic for $|z - z_0| > r$ and tends to 0 as $z \to \infty$. Thus we obtain the decomposition $f(z) = f_0(z) + f_1(z)$ for $r < |z - z_0| < s$.

Definition 6.2. If a function $f(z) = f_0(z) + f_1(z)$ can be decomposed using Laurent Decomposition. Then we can express the function using its **Laurent series expansion**

$$f(z) = \sum_{k=-\infty}^{\infty} a_k (z - z_0)^k, \qquad \rho < |z - z_0| < \sigma,$$

which converges uniformly and absolutely on $r \leq |z - z_0| \leq s$ where $\rho < r < s < \sigma$. We can also express $f_0(z)$ as a power series in $z - z_0$,

$$f_0(z) = \sum_{k=0}^{\infty} a_k(z - z_0), \qquad |z - z_0| < \sigma,$$

where the series converges absolutely, and for any $s < \sigma$ it converges uniformly for $|z - z_0| \le s$. Further, we can express $f_1(z)$ as a series of negative powers of $z - z_0$,

$$f_1(z) = \sum_{k=-\infty}^{-1} a_k (z - z_0)^k, \qquad |z - z_0| > \rho.$$

This series converges absolutely, and for any $r > \rho$ it converges uniformly for $|z - z_0| \ge r$.

Theorem 6.3 (Laurent Series Expansion). Suppose $0 \le \rho < \sigma \le \infty$ and suppose f(z) is analytic for $\rho < |z - z_0| < \sigma$. Then f(z) has a Laurent series expansion that converges absolutely at each point on the annulus and converges uniformly on each closed subannulus $r \le |z - z_0| < s$ where $\rho < r < s < \sigma$. The coefficients are uniquely determined by f(z) for any fixed $r, \rho < r < \sigma$ and are given by

$$a_n = \frac{1}{2\pi i} \oint_{|z-z_0|=r} \frac{f(z)}{(z-z_0)^{n+1}} \, dz, \qquad -\infty < n < \infty.$$

6.2 Isolated Singularities of an Analytic Function

Definition 6.4. A point z_0 is an **isolated singularity** of f(z) if f(z) is analytic in some punctured disk $\{0 < |z - z_0| < r\}$ centered at z_0 . Suppose that f(z) has an isolated singularity at z_0 . Then f(z) has a Laurent series expansion

$$f(z) = \sum_{k=-\infty}^{\infty} a_k (z - z_0)^k, \qquad 0 < |z - z_0| < r.$$

Definition 6.5. The isolated singularity of f(z) at z_0 is defined to be **removable singularity** if $a_k = 0$ for all k < 0. In this case, the Laurent series (6.1) becomes a power series

$$f(z) = \sum_{k=0}^{\infty} a_k (z - z_0)^k, \qquad 0 < |z - z_0| < r$$

If we define $f(z_0) = a_0$, the function f(z) becomes analytic on the entire disk $\{|z - z_0| < r\}$.

Definition 6.6 (Riemann's Theorem of Removable Singularities). Let z_0 be an isolated singularity of f(z). If f(z) is bounded near z_0 , then f(z) has a removable singularity at z_0 .

Definition 6.7. The isolated singularity of f(z) at z_0 is defined to be a **pole** if there is N > 0 such that $a_{-N} \neq 0$, but $a_k = 0$ for all k < -N. The integer N is the **order** of the pole. In the case the Laurent series (6.1) becomes

$$f(z) = \sum_{k=-N}^{\infty} a_k (z-z_0)^k = \frac{a_{-N}}{(z-z_0)^N} + \dots + \frac{a_{-1}}{z-z_0} + a_0 + a_1 (z-z_0).$$

The sum of the negative powers,

$$P(z) = \sum_{k=-N}^{-1} a_k (z - z_0)^k = \frac{a_{-N}}{(z - z_0)^N} + \dots + \frac{a_{-1}}{z - z_0},$$

is called the **principal part** of f(z) at the pole z_0 . The principal part P(z) coincides with the summand $f_1(z)$ in the Laurent decomposition $f(z) = f_0(z) + f_1(z)$ given in the preceding section. The bad behavior of f(z) at z_0 is incorporated into P(z), in the sense that f(z) - P(z) is analytic at z_0 . A pole of order one is called a **simple pole**, and a pole of order two is called a **double pole**.

Theorem 6.8. Let z_0 be an isolated singularity of f(z). Then z_0 is a pole of f(z) of order N if and only if $f(z) = g(z)/(z-z_0)^N$, where g(z) is analytic at z_0 and $g(z_0) \neq 0$.

Theorem 6.9. Let z_0 be an isolated singularity of f(z). Then z_0 is a pole of f(z) of order N if and only if 1/f(z) is analytic at z_0 and has a zero of order N.

Definition 6.10. We say that a function f(z) is meromorphic on a domain D if f(z) is analytic on D except possibly at isolated singularities, each of which is a pole. A meromorphic function f at z_0 is said to

have order N at z_0 if $f(z) = (z - z_0)^N g(z)$ for some analytic function g at z_0 such that $g(z_0) \neq 0$. The order of the function 0 is defined to be $+\infty$. If there are infinitely many poles of f(z) in D, then we can arrange them in a sequence that accumulates only at the boundary of D.

Lemma 6.11. Sums and products of meromorphic functions are meromorphic. Quotients of meromorphic functions are meromorphic, provided the denominator is not identically zero.

Theorem 6.12. Let z_0 be an isolated singularity of f(z). Then z_0 is a pole if and only if $|f(z)| \to \infty$ as $z \to z_0$.

Definition 6.13. The isolated singularity of f(z) at z_0 is defined to be an **essential singularity** if $a_k \neq 0$ for infinitely many k < 0. Thus an isolated singularity that is neither removable nor a pole is declared to be essential.

Theorem 6.14 (Casorati-Weierstrass Theorem). Suppose z_0 is an essential isolated singularity of f(z). Then for every complex number w_0 , there is a sequence $z_n \to z_0$ such that $f(z_n) \to w_0$.

6.3 Isolated Singularity at Infinity

Definition 6.15. We say that f(z) has an **isolated singularity at** ∞ if f(z) is analytic outside some bounding set, that is, if there is R > 0 such that f(z) is analytic for |z| > R. Thus f(z) has an isolated singularity at ∞ if and only if g(w) = f(1/w) has an isolated singularity at w = 0.

We classify the isolated singularity of f(z) at ∞ according to the isolated singularity of g(w) at w = 0. Suppose f(z) has the Laurent series expansion

$$f(z) = \sum_{k=-\infty}^{\infty} b_k z^k, \qquad |z| > R$$

The singularity of f(z) at $f(z) = \infty$ is **removable** if $b_k = 0$ for all k > 0 in which case f(z) is analytic at ∞ . The singularity of f(z) at $f(z) = \infty$ is **essential** if $b_k \neq 0$ for infinitely many k > 0. For fixed $N \ge 1$, f(z) has a **pole** of order N at ∞ if $b_N \ge 0$ while $b_k = 0$ for k > N.

Suppose f(z) has a pole of order N at ∞ . The Laurent series expansion of f(z) becomes

$$f(z) = b_N z^N + b_{N-1} z^{N-1} + \dots + b_1 z + b_0 + \frac{b_{-1}}{z} + \dots, \qquad |z| > R,$$

where $b_N \neq 0$. We defined the **principal part of** f(z) at ∞ to be the polynomial

$$P(z) = b_N z^N + b_{N-1} z^{N-1} + \dots + b_1 z + b_0.$$

6.4 Partial Fraction Decomposition

Theorem 6.16. A meromorphic function on the extended complex plane \mathbb{C}^* is rational.

Definition 6.17. If f(z) is analytic at ∞ , we define $P_{\infty}(z)$ to be the constant function $f(\infty)$. Otherwise, f(z) has a pole at ∞ and we define $P_{\infty}(z)$ to be the principal part of f(z) at ∞ . Let z_1, \ldots, z_m be the poles of f(z) in the finite complex plane \mathbb{C} , and let $P_k(z)$ be the principal part of f(z) at z_k . Then

$$f(z) = P_{\infty}(z) + \sum_{j=1}^{m} P_j(z).$$
(6.2)

The decomposition (6.2) is the called the **partial fractions decomposition** of the rational function f(z).

Theorem 6.18. Every rational function has a partial frations decomposition, expressing it as a sum of a polynomial in z and its principal parts at each of its poles in the finite complex plane.

6.5 Periodic Functions

Definition 6.19. A complex number ω is a **period** of a function f(z) if f(z+w) = f(z) whenever defined. The function f(z) is **periodic** if it has period $\omega \neq 0$.

Theorem 6.20. If f(z) is analytic on the horizontal strip $\{\alpha < \text{Im}(z) < \beta\}$, and f(z) is periodic with period 1, then f(z) can be expanded in an absolutely convergent series of exponentials

$$f(z) = \sum_{k=-\infty}^{\infty} a_k e^{2\pi i k z}, \qquad \alpha < \operatorname{Im}(z) < \beta$$

The series converges uniformly on any smaller strip $\{\alpha_0 \leq \text{Im}(z) \leq \beta_0\}$ where $\alpha < \alpha_0 < \beta_0 < \beta$.

Theorem 6.21. Suppose f(z) is analytic on the half-plane $\{\text{Im}(z) > \alpha\}$, and f(z) is periodic with period 1. If f(z) is bounded as $\text{Im}(z) \to +\infty$, then f(z) can be expanded in an absolutely convergent series of exponentials

$$f(z) = \sum_{k=0}^{\infty} a_k e^{2\pi i k z}, \qquad \text{Im}(z) > \alpha.$$

The series converges uniformly on any smaller half-plane $\{\text{Im}(z) \ge \alpha_0\}$, where $\alpha_0 > \alpha$.

Theorem 6.22. Suppose that f(z) is a nonconstant meromorphic function on the complex plane that is periodic. Either there is a period ω_1 for f(z) such that the periods of f(z) are the integral multiples $n\omega_1$, $-\infty < m < \infty$, or there are two periods ω_1 and ω_2 for f(z) that do not lie on the same line through the origin such that the periods of f(z) are the integral combinations $m\omega_1 + n\omega_2$, $-\infty < m, n < \infty$.

Definition 6.23. In the case that the periods of f(z) all lie on the same straight line through the origin, we say that f(z) is simply periodic. Otherwise, we say that f(z) is doubly periodic.

Theorem 6.24. An entire function that is doubly periodic is constant.

6.6 Fourier Series

Definition 6.25. A complex Fourier series is a two-tailed series of the form

$$\sum_{k=-\infty}^{\infty} c_k e^{ik\theta} = \dots + c_{-2} e^{-2i\theta} + c_{-1} e^{-i\theta} + c_0 + c_1 e^{i\theta} + c_2 e^{2i\theta} + \dots$$
(6.3)

If the Laurent series

$$f(z) = \sum_{k=-\infty}^{\infty} a_k z^k$$

converges uniformly on the circle $\{|z| = r\}$, then

$$f(re^{i\theta}) = \sum_{k=-\infty}^{\infty} a_k r^k e^{ik\theta}$$

is the Fourier series expansion of $f(re^{i\theta})$, regarded as a function of θ . The Fourier coefficients of the expansion are the coefficients $c_k = a_k r^k$.

Definition 6.26. We define the **Fourier coefficients** of any piecewise continuous function (or any integral function) $f(e^{i\theta})$ to be

$$c_k = \int_{-\pi}^{\pi} f(e^{i\theta}) e^{-ik\theta} \frac{d\theta}{2\pi}, -\infty < k < \infty,$$
(6.4)

and we associate $f(e^{i\theta})$ the Fourier series

$$f(e^{i\theta}) \sim \sum_{k=-\infty}^{\infty} c_k e^{ik\theta},$$

where c_k is defined by (6.4). We call $\sum c_k e^{ik\theta}$ the Fourier series of $f(e^{i\theta})$.

Theorem 6.27. If $f(e^{i\theta})$ is piecewise continuous (or more generally, square-integrable), with Fourier series $f(e^{i\theta}) \sim \sum_{k=-\infty}^{\infty} c_k e^{ik\theta}$, then for $m, n \ge 0$ we have

$$\sum_{k=-m}^{n} |c_k|^2 + \int_{-\pi}^{\pi} \left| f(e^{i\theta}) - \sum_{k=-m}^{n} c_k e^{ik\theta} \right|^2 \frac{d\theta}{2\pi} = \int_{-\pi}^{\pi} \left| f(e^{i\theta}) \right|^2 \frac{d\theta}{2\pi}.$$

Theorem 6.28 (Bessel's Inequality). If $f(e^{i\theta})$ is piecewise continuous (or more generally, square-integrable), with Fourier series $f(e^{i\theta}) \sim \sum_{k=-\infty}^{\infty} c_k e^{ik\theta}$, then

$$\sum_{k=-\infty}^{\infty} |c_k|^2 \le \int_{-\pi}^{\pi} \left| f(e^{i\theta}) \right|^2 \frac{d\theta}{2\pi}.$$

Theorem 6.29. Suppose $f(e^{i\theta})$ is piecewise continuous (or more generally, square-integrable), with Fourier series $f(e^{i\theta}) \sim \sum_{k=-\infty}^{\infty} c_k e^{ik\theta}$. If $f(e^{i\theta})$ is differentiable at θ_0 , then the Fourier series of $f(e^{i\theta})$ converges to $f(e^{i\theta_0})$ at $\theta = \theta_0$,

$$f(e^{i\theta_0}) = \sum_{-\infty}^{\infty} c_k e^{ik\theta_0} = \lim_{m,n\to\infty} \sum_{k=-m}^n c_k e^{ik\theta_0}.$$

Theorem 6.30. Suppose $f(e^{i\theta})$ is continuously differentiable function of θ , with Fourier series $f(e^{i\theta}) \sim \sum_{k=-\infty}^{\infty} c_k e^{ik\theta}$. Then the Fourier series of the derivative of $f(e^{i\theta})$ is obtained by differentiating term by term,

$$\frac{d}{d\theta}f(e^{i\theta})\sim\sum ikc_ke^{ik\theta}.$$

Corollary 6.31. If $f(e^{i\theta})$ is an *n*-times continuously differentiable function of θ , with Fourier series $f(e^{i\theta}) \sim \sum_{k=-\infty}^{\infty} c_k e^{ik\theta}$, then $\sum_{k=-\infty}^{\infty} k^{2n} |c_k|^2 < \infty$. Further, $k^n c_k \to 0$ as $k \to \pm \infty$.

Theorem 6.32. Suppose $f(e^{i\theta})$ is a twice continuously differentiable function of θ . Then the Fourier series of $f(e^{i\theta})$ converges to $f(e^{i\theta})$ uniformly in θ .

7 The Residue Calculus

7.1 The Residue Theorem

Definition 7.1. Suppose z_0 is an isolated singularity of f(z) and that f(z) has a Laurent series

$$f(z) = \sum_{n=-\infty}^{\infty} a_n (z - z_0)^n, \qquad 0 < |z - z_0| < \rho,$$

We define the **residue** of f(z) at z_0 to be the coefficient a_{-1} of $1/(z-z_0)$ in this Laurent expansion,

$$\operatorname{Res}\left[f(z), z_{0}\right] = a_{-1} = \frac{1}{2\pi i} \oint_{|z-z_{0}|=r} f(z) \, dz, \tag{7.1}$$

where r is any fixed radius satisfying $0 < r < \rho$.

Theorem 7.2. Let D be a bounded domain in the complex plane with piecewise smooth boundary. Suppose that f(z) is analytic on $D \cup \partial D$, except for a finite number of isolated singularities z_1, \ldots, z_m in D. Then

$$\int_{\partial D} f(z) dz = 2\pi i \sum_{j=1}^{m} \operatorname{Res} \left[f(z), z_j \right].$$
(7.2)

We give four useful rules for calculating residues: (1) If f(x) has a simple pole at x, then

(1) If f(z) has a simple pole at z_0 , then

Res
$$[f(z), z_0] = \lim_{z \to z_0} (z - z_0) f(z).$$

(2) If f(z) has a double pole at z_0 , then

Res
$$[f(z), z_0] = \lim_{z \to z_0} \frac{d}{dz} [(z - z_0)^2 f(z)].$$

(3) If f(z) and g(z) are analytic at z_0 , and if g(z) has a simple zero at z_0 , then

Res
$$\left[\frac{f(z)}{g(z)}, z_0\right] = \frac{f(z_0)}{g'(z_0)}$$

(4) If g(z) is analytic and has a simple zero at z_0 , then

Res
$$\left[\frac{1}{g(z)}, z_0\right] = \frac{1}{g'(z_0)}$$
.

7.2 Integrals Featuring Rational Functions

Remark. The residue theorem can be used to evaluate integral of the form

$$\int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} \, dx.$$

For the integral to converge, P(z) and Q(z) must be polynomials and Q(z) has no zeroes on the real axis. It is also required that

$$\deg Q(z) \ge \deg P(z) + 2$$

Then evaluating the integral on the half-disk in the upper half-plane and letting the radius go to ∞ , we have

$$\int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} dx = 2\pi i \sum \operatorname{Res} \left[\frac{P(z)}{Q(z)}, z_j \right].$$

Integrals of rational functions with a trigonometric multiplier can also be computed using the residue theorem. For example,

$$\int_{-\infty}^{\infty} \frac{P(x)}{Q(x)} \cos(ax) \, dx = \pi e^{-a}.$$

Here, we replace $\cos(ax)$ with $e^{iz} = e^{-y}$ which is bounded above in magnitude by 1 in the upper half-plane.

7.3 Integral of Trigonometric Functions

Remark. Integrals with polar coordinates can be converted into a line integral on a disk in the complex plane. We use the following parameterization

$$d\theta = \frac{dz}{iz}$$

for the differential and the exponential forms of $\sin z$ and $\cos z$.

$$\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2} = \frac{z + 1/z}{2}$$
$$\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i} = \frac{z - 1/z}{2i}$$

Therefore,

$$\int_{0}^{2\pi} \frac{d\theta}{a + \cos\theta} = \oint_{|z|=1} \frac{1}{a + \frac{1}{2}(z + 1/z)} \frac{dz}{iz} = \frac{2}{i} \oint_{|z|=1} \frac{dz}{z^2 + 2az + 1}$$

can be computed using the residue theorem.

7.4 Integrands with Branch Points

This section contains no definitions or theorems.

7.5 Fractional Residues

Theorem 7.3 (Fractional Residue Theorem). If z_0 is a simple pole of f(z), and C_{ϵ} is an arc of the circle $\{|z - z_0| = \epsilon\}$ of angle α , then

$$\lim_{\epsilon \to 0} \int_{C_{\epsilon}} f(z) \, dz = \alpha i \operatorname{Res} \left[f(z), z_0 \right].$$

7.6 Principal Values

Definition 7.4. An integral $\int_a^b f(x) dx$ is **absolutely convergent** if the (proper or improper) integral $\int_a^b |f(x)| dx$ is finite. The integral is **absolutely divergent** if $\int_a^b |f(x)| dx = +\infty$.

Definition 7.5. Suppose that f(x) is continuous for $a \le x < x_0$ and for $x_0 < x \le b$. We define the **principal value** of the integral $\int_a^b f(x) dx$ to be

$$\operatorname{PV} \, \int_{a}^{b} f(x) \, dx = \lim_{\epsilon \to 0} \left(\int_{a}^{x_{0}-\epsilon} + \int_{x_{0}+\epsilon}^{b} \right) f(x) \, dx,$$

provided that the limit exists. The principal value of the integral coincides with the usual value of the (proper or improper) integral if f(x) is absolutely integrable.

Definition 7.6. Let u(s) is an integral function on the real line. We define the **Hilbert transform** by

$$(Hu)(t) = \mathrm{PV} \, \int_{-\infty}^{\infty} \frac{u(s)}{s-t} \, ds, \qquad -\infty < t < \infty.$$

If u(s) is extended appropriately to be harmonic in the upper half-plane, then (Hu)(s) is the boundary value function of its harmonic conjugate.

7.7 Jordan's Lemma

Lemma 7.7 (Jordan's Lemma). If Γ_R is the semicircular contour $z(\theta) = Re^{i\theta}, 0 \le \theta \le \pi$, in the upper half-plane, then

$$\int_{\Gamma_R} |e^{iz}| |dz| < \pi.$$
(7.3)

For the parameterization $z(\theta) = Re^{i\theta}$ we have $|e^{iz}| = e^{R\sin\theta}$ and $|dz| = Rd\theta$, so the estimate (7.3) becomes

$$\int_0^\pi e^{-R\sin\theta} \, d\theta < \frac{\pi}{R}$$

7.8 Exterior Domains

Definition 7.8. An exterior domain is a domain D in the complex plane that includes all large z, that is, D includes all z such that $|z| \ge R$ for some R.

Theorem 7.9. Let D be an exterior domain with piecewise smooth boundary. Suppose that f(z) is analytic on $D \cup \partial D$, except for a finite number of isolated singularities z_1, \ldots, z_m in D, and let a_{-1} be the coefficient of 1/z in the Laurent expansion $f(z) = \sum a_k z^k$ that converges for |z| > R. Then

$$\int_{\partial D} f(z) \, dz = -2\pi i a_{-1} + 2\pi i \sum_{j=1}^{m} \operatorname{Res} \left[f(z), z_j \right]. \tag{7.4}$$

Definition 7.10. Suppose now that f(z) is analytic for $|z| \ge R$, with Laurent expansion

$$f(z) = \sum_{n=-\infty}^{\infty} a_n x^n, \qquad |z| \ge R.$$

We define the **residue of** f(z) at ∞ to be

$$\operatorname{Res}\left[f(z),\infty\right] = -a_{-1}.$$

The formula (7.4) becomes

$$\int_{\partial D} f(z) dz = -2\pi \operatorname{Res} \left[f(z), \infty \right] + 2\pi i \sum_{j=1}^{m} \operatorname{Res} \left[f(z), z_j \right].$$

8 The Logarithmic Integral

8.1 The Argument Principle

Definition 8.1. Suppose f(z) is analytic on a domain D. For a curve γ in D such that $f(z) \neq 0$ on γ , we refer to

$$\frac{1}{2\pi i} \int_{\gamma} \frac{f'(z)}{f(z)} dz = \frac{1}{2\pi i} \int_{\gamma} d\log f(z)$$

as the logarithmic integral of f(z) along γ . Thus the logarithmic integral measures the change of log f(z) along the curve γ .

Theorem 8.2. Let *D* be a bounded domain with piecewise smooth boundary ∂D , and let f(z) be a meromorphic function on *D* that extends to be analytic on ∂D , such that $f(z) \neq 0$ on ∂D . Then

$$\frac{1}{2\pi i} \int_{\partial D} \frac{f'(z)}{f(z)} \, dz = N_0 - N_\infty$$

where N_0 is the number of zeros of f(z) in D and N_{∞} is the number of poles of f(z) in D, counting multiplicities.

Definition 8.3. Evaluating the logarithmic integral yields

$$\frac{1}{2\pi i}\int_{\gamma}d\log f(z) = \frac{1}{2\pi i}\int_{\gamma}d\log |f(z)| + \frac{1}{2\pi}\int_{\gamma}d\arg(f(z)).$$

The differential $d \log |f(z)|$ is exact. If we parameterize γ by $\gamma(t) = x(t) + iy(t), a \le t \le b$, then

$$\int_{\gamma} d\log |f(z)| = \log |f(\gamma(b))| - \log |f(\gamma(a))|$$

depends solely on $\gamma(a)$ and $\gamma(b)$. In particular, the integral is 0 on any closed curve. The differential $d \arg f(z)$ is closed but not exact. Integrating on γ gives us

$$\int_{\gamma} d\arg(f(z)) = \arg f(\gamma(b)) - \arg f(\gamma(a)).$$
(8.1)

The quantity (8.1) is referred to as the **increase in the argument of** f(z) along γ . It is defined for any path γ in D providing there are no zeros on poles on the path. If a bounded domain D has a boundary ∂D consists of a finite number of piecewise-smooth curves, then we define the **increase in the argument of** f(z) around the boundary of D to be the sum of its increase around the closed curves in ∂D .

Theorem 8.4. Let D be a bounded domain with piecewise smooth boundary ∂D , and let f(z) be a meromorphic function on D that extends to be analytic on ∂D , such that $f(z) \neq 0$ on ∂D . Then the increase in the argument on f(z) around the boundary of D is 2π times the number of zeros minus the number of poles of f(z) in D,

$$\int_{\partial D} d \arg(f(z)) = 2\pi (N_0 - N_\infty).$$

8.2 Rouché's Theorem

Theorem 8.5 (Rouché's Theorem). Let D be a bounded domain with piecewise smooth boundary ∂D . Let f(z) and h(z) be analytic on $D \cup \partial D$. If |h(z)| < |f(z)| for $z \in \partial D$, then f(z) and f(z) + h(z) have the same number of zeros in D, counting multiplicities.

8.3 Hurwitz's Theorem

Theorem 8.6 (Hurwitz's Theorem). Suppose $\{f_k(z)\}$ is a sequence of analytic functions on a domain D that converges normally on D to f(z), and suppose that f(z) has a zero of order N at z_0 . Then there exists $\rho > 0$ such that for large k, $f_k(z)$ has exactly N zeros in the disk $\{|z - z_0| < \rho\}$ counting multiplicity, and these zeros converge to z_0 as $k \to \infty$.

Theorem 8.7. We say that a function is **univalent** on a domain D if it is analytic and one-to-one on D.

Theorem 8.8. Suppose $\{f_k(z)\}$ is a sequence of univalent functions on a domain D that converges normally on D to a function f(z). Then either f(z) is univalent or f(z) is constant.

8.4 Open Mapping and Inverse Function Theorems

Definition 8.9. Let f(z) be a meromorphic function on a domain D. We say that f(z) attains the value $w_0 m$ times at z_0 if $f(z) - w_0$ has a zero of order m at z_0 . We make the usual modifications to cover the

cases $z_0 = \infty$ and $w_0 = \infty$, so that f(z) attains a finite value w_0 m times at $z_0 = \infty$ if $f(1/z) - w_0$ has a zero of order m at z = 0, and f(z) attains the value ∞ m times at z_0 if z_0 is a pole of f(z) of order m.

Theorem 8.10 (Open Mapping Theorem for Analytic Functions). If f(z) is analytic on a domain D, and f(z) is not constant, then f(z) maps open sets to open sets, that is f(U) is open for each open subset of D.

Theorem 8.11 (Inverse Function Theorem). Suppose f(z) is analytic for $|z - z_0| \leq \rho$ and satisfies $f(z_0) = w_0$, $f'(z_0) \neq 0$, and $f(z) \neq w_0$ for $0 < |z - z_0| \leq \rho$. Let $\delta > 0$ be chosen such that $|f(z) - w_0| \geq \delta$ for $|z - z_0| = \rho$. Then for each w such that $|w - w_0| < \delta$, there is a unique z satisfying $|z - z_0| < \rho$ and f(z) = w. Writing $z = f^{-1}(w)$, we have

$$f^{-1}(w) = \frac{1}{2\pi i} \int_{|\zeta - z_0| = \rho} \frac{\zeta f'(\zeta)}{f(\zeta) - w} \, d\zeta, \qquad |w - w_0| < \delta.$$

8.5 Critical Points

Definition 8.12. Let f(z) be a nonconstant analytic function on a domain D. A point z_0 is called a **critical point** of f(z) if $f'(z_0) = 0$. The value $f(z_0) = w_0$ is called a **critical value** of f(z). We define the **order** of the critical point z_0 to be the order of zero of f'(z) at z_0 . Since the critical points are the zeros of the nonconstant analytic function f'(z), critical points are isolated.

Theorem 8.13. Let f(z) be analytic at z_0 . Suppose z_0 is a critical point of order m-1 for f(z), with critical value $f(z_0) = w_0$. Let $\rho > 0$ satisfy $f(z) \neq w_0$ for $0 < |z - z_0| \le \rho$, and let $\delta > 0$ satisfy $|f(z) - w_0| \ge \delta$ for $|z - z_0| = \rho$. Then for each w such that $0 < |w - w_0| < \delta$, the equation f(z) = w has exactly m distinct solutions $z_1(w), \ldots, z_m(w)$ in the disk $\{|z - z_0| < \rho\}$. The functions $z_1(w), \ldots, z_m(w)$ can be chosen to depend analytically on w in the slit disk $\{|w - w_0| < \delta\} \setminus (w_0 - \delta, w_0]$. They form the m branches of an analytic function z = z(w) on an m-sheeted Riemann surface over the punctured disk $\{0 < |w - w_0| < \delta\}$. The $z_i(w)$'s are the solutions of a polynomial equation

$$z^{m} + a_{m-1}(w)z^{m-1} + \dots + a_{1}(w)z + a_{0}(w) = 0$$

with coefficients $a_i(w)$ that are analytic for $|w - w_0| < \delta$.

8.6 Winding Numbers

Definition 8.14. Let $\gamma(t), a \leq t \leq b$ be a closed path in *D*. We define the **trace of** γ to be the image $\Gamma = \gamma([a, b])$ of γ . For $z_0 \neq \Gamma$, we define the **winding number** $W(\gamma, z_0)$ of γ around z_0 to be the increase in the argument of $z - z_0$ around γ , normalized by dividing by 2π . If γ is piecewise smooth, the winding number is the integer

$$W(\gamma, z_0) = \frac{1}{2\pi i} \int_{\gamma} \frac{dz}{z - z_0} = \frac{1}{2\pi} \int_{\gamma} d \arg(z - z_0), \qquad z_0 \neq \Gamma.$$

Theorem 8.15. Let $\gamma(t), a \leq t \leq b$, be a closed path in the complex plane, and let $\Gamma = \gamma([a, b])$ be its trace. The winding number $W(\gamma, \zeta)$ is constant on each connected component of $\mathbb{C} \setminus \Gamma$. Further, $W(\gamma, \zeta) = 0$ for all ζ in the unbounded component of $\mathbb{C} \setminus \Gamma$.

Theorem 8.16. If f(z) is analytic on a domain D, then $\int_{\gamma} f(z) dz = 0$ for each closed path γ in D such that $W(\gamma, \zeta) = 0$ for all $\zeta \in \mathbb{C} \setminus D$.

Theorem 8.17. Let f(z) be analytic on a domain D, and let γ be a closed path in D with trace $\Gamma = \gamma([a, b])$. If $W(\gamma, \zeta) = 0$ for all $\zeta \in \mathbb{C} \setminus D$, then

$$\frac{1}{2\pi i} \int_{\gamma} \frac{f(z)}{z - z_0} \, dz = W(\gamma, z_0) f(z_0) \qquad z_0 \in D \setminus \Gamma.$$

8.7 The Jump Theorem for Cauchy Integrals

Definition 8.18. Suppose γ is a piecewise smooth curve with trace Γ , and let f(z) be a continuous function on Γ . We define the **Cauchy integral of** f(z) along γ to be the function $F(\zeta)$ defined off Γ by

$$F(\zeta) = \frac{1}{2\pi i} \int_{\gamma} \frac{f(z)}{z - \zeta} dz, \qquad \zeta \in \mathbb{C} \setminus \Gamma.$$
(8.2)

We have seen that the Cauchy integral $F(\zeta)$ is analytic on $\mathbb{C} \setminus \Gamma$, and $F(\zeta)$ vanishes at ∞ .

Theorem 8.19 (Jump Theorem for Cauchy Integrals). Suppose that Γ is a smooth curve that passes through z_0 , and f(z) is a continuous function on Γ that is analytic at z_0 . Let U be a small disk containing z_0 such that f(z) is analytic on U and such that Γ divides U into the two components. We set U_+ to be the open domain on the right side of γ as we traverse the curve in the positive direction, and U_- to be the open domain on the left side. Then there are analytic functions $F_+(\zeta)$ and $F_-(\zeta)$ on U satisfying

$$F_{-}(\zeta) - F_{+}(\zeta) = f(\zeta), \qquad \zeta \in U,$$

and such that the Cauchy integral $F(\zeta)$ of f(z), defined by (8.2), satisfies

$$F(\zeta) = \begin{cases} F_+(\zeta), & \zeta \in U_+, \\ F_-(\zeta), & \zeta \in U_-. \end{cases}$$

Thus as ζ crosses Γ from right to left (from U_+ to U_-) the values of the Cauchy integral $F(\zeta)$ jump by $f(\zeta)$,

$$F_{-}(\zeta) = F_{+}(\zeta) + f(\zeta), \qquad \zeta \in U.$$

Theorem 8.20 (Jump Theorem for Winding Numbers). Let γ be a closed path with trace Γ , and let $z_0 = \gamma(t_0) \in \Gamma$. Suppose that $\gamma(t)$ is continuously differentiable for t near t_0 , with $\gamma'(t_0) \neq 0$. Let Ube a small disk centered at z_0 that is divided into two components U_{\pm} by a segment γ_0 on γ as above, and suppose that $\gamma \setminus \gamma_0$ does not enter U. Then as $\zeta \in U$ crosses Γ from right to left (from U_+ to U_-), the winding number $W(\gamma, \zeta)$ jumps by +1,

$$W(\gamma, \zeta_{-}) = W(\gamma, \zeta_{+}) + 1, \qquad \zeta_{-} \in U_{-}, \zeta_{+} \in U_{+},$$

Theorem 8.21 (Jordan Curve Theorem for Smooth Curves). Let γ be a piecewise smooth simple closed curve in the complex plane \mathbb{C} , and let $\Gamma = \gamma([a, b])$ be its trace. Then Γ divides the complex plane into two connected components, one bounded and the other unbounded, each of which has Γ as its boundary. Further, $W(\gamma, \zeta) = 0$ if ζ is in the unbounded component of $\mathbb{C} \setminus \Gamma$, and $W(\gamma, \zeta) = \pm 1$ if ζ is in the bounded component of $\mathbb{C} \setminus \Gamma$, where the choice of sign depends on the orientation of γ .

8.8 Simply Connected Domains

Definition 8.22. Let $\gamma(t)$, $a \le t \le b$, be a closed path in a domain D. We say that γ is **deformable to a point** if there are closed paths $\gamma_s(t)$, $a \le t \le b$, $0 \le s \le 1$, in D such that $\gamma_s(t)$ depends continuously on both s and t, $\gamma_0 = \gamma$, and $\gamma_1(t) = z_1$ is the constant path at some point $z_1 \in D$. The domain D is **simply connected** if every closed path in D can be deformed to a point.

Lemma 8.23. Let $\gamma(t)$, $0 \le t \le 1$, be a closed path in D, with $z_0 = \gamma(0) = \gamma(1)$. Suppose that γ can be deformed continuously to a point in D. Then there is a continuous family of closed paths γ_s , $0 \le s \le 1$, such that $\gamma_0 = \gamma, \gamma_1$ is the constant path at z_0 , and each path γ_s starts and ends at z_0 .

Definition 8.24. Let X be a subset of the extended complex plane \mathbb{C}^* . We say that X is **connected** if every continuous integer-valued function on X is constant.

Theorem 8.25. The following properties are equivalent, for a domain D in the complex plane:

- (a) D is simply connected,
- (b) every closed differential on D is exact,
- (c) for each $z_0 \in \mathbb{C} \setminus D$, there is an analytic branch of $\log(z z_0)$ defined on D,
- (d) each closed curve γ in D has winding number $W(\gamma, z_0) = 0$ about all points $z_0 \in \mathbb{C} \setminus D$,
- (e) the complement of D in the extended complex plane \mathbb{C}^* is connected.

9 The Schwarz Lemma and Hyperbolic Geometry

9.1 The Schwarz Lemma

Theorem 9.1 (Schwarz Lemma). Let f(z) be analytic for |z| < 1. Suppose $|f(z)| \le 1$ for all |z| < 1, and f(0) = 0. Then

$$|f(z)| \le |z|, \qquad |z| < 1.$$
 (9.1)

Further, if equality holds in (9.1) at some point $z_0 \neq 0$, then $f(z) = \lambda z$ for some constant λ of unit modulus.

Corollary 9.2. An analogous estimate holds in any disk. If f(z) is analytic for $|z - z_0| < R$, $f(z) \le M$, and $f(z_0) = 0$, then

$$|f(z)| \le \frac{M}{R}|z - z_0|, \qquad |z - z_0| < R,$$

Theorem 9.3. Let f(z) be analytic for |z| < 1. If $|f(z)| \le 1$ for |z| < 1, and f(0) = 0, then

 $|f'(0)| \le 1,$

with equality if and only if $f(z) = \lambda z$ for some constant λ with $|\lambda| = 1$.

9.2 Conformal Self-Maps of the Unit Disk

Definition 9.4. We denote by \mathbb{D} the open unit disk in the complex plane, $\mathbb{D} = \{|z| < 1\}$. A conformal self-map of the unit disk is an analytic function from \mathbb{D} to itself that is one-to-one and onto.

Remark. The composition of two conformal self-maps is again a conformal self-map, and the inverse of a conformal self-map is a conformal self-map. The conformal self-maps from a group with composition as the group operation; the group identity is the identity map g(z) = z.

Lemma 9.5. If g(z) is a conformal self-map of the unit disk \mathbb{D} such that g(0) = 0, then g(z) is a rotation, that is, $g(z) = e^{i\varphi}z$ for some fixed φ , $0 \le \varphi \le 2\pi$.

Theorem 9.6. The conformal self-maps of the open unit disk \mathbb{D} are precisely the fractional linear transformations of the form

$$f(z) = e^{i\varphi} \frac{z-a}{1-\overline{a}z}, \qquad |z| < 1,$$

where a is complex, |a| < 1, and $0 \le \varphi \le 2\pi$.

Theorem 9.7 (Pick's Lemma). If f(z) is analytic and satisfies |f(z)| < 1 for |z| < 1, then

$$|f'(z)| \le \frac{1 - |f(z)|^2}{1 - |z|^2}, \qquad |z| < 1.$$
(9.2)

If f(z) is a conformal self-map of \mathbb{D} , then equality holds in (9.2); otherwise, there is a strict inequality for all |z| < 1.

9.3 Hyperbolic Geometry

Definition 9.8. Suppose w = f(z) is a conformal self-map of the open unit disk \mathbb{D} . From Pick's lemma we then have equality in (9.2),

$$\left|\frac{dw}{dz}\right| = \frac{1 - |w|^2}{1 - |z|^2}.$$

In the differental form this becomes

$$\frac{|dw|}{1-|w|^2} = \frac{|dz|}{1-|z|^2},$$

which means that if γ is any smooth curve in \mathbb{D} , and w = f(z) is a conformal self-map of \mathbb{D} , then

$$\int_{f \circ \gamma} \frac{|dw|}{1 - |w|^2} = \int_{\gamma} \frac{|dz|}{1 - |z|^2}.$$
(9.3)

Thus to obtain a length function that is invariant under conformal self-maps of \mathbb{D} , we define the **length of** γ in the hyperbolic metric by

hyperbolic length of
$$\gamma = 2 \int_{\gamma} \frac{|dz|}{1 - |z|^2}.$$
 (9.4)

Remark. The factor 2 is often ommitted. (It adjusts the metric so that its curvature is -1.) The identity (9.3) shows that $f \circ \gamma$ has the same hyperbolic length as γ for any conformal self-map f(z) of \mathbb{D} . Thus hyperbolic lengths are invariant under conformal self-maps of \mathbb{D} .

Definition 9.9. We define the hyperbolic distance $\rho(z_0, z_1)$ from z_0 to z_1 to be the infimum of the hyperbolic lengths of all piecewise smooth curves in \mathbb{D} from z_0 to z_1 . Since conformal self-maps of \mathbb{D} preserve the hyperbolic lengths of curves, they also preserve hyperbolic distances; that is, for any conformal self-map w = f(z) on \mathbb{D} ,

$$\rho(f(z_0), f(z_1)) = \rho(z_0, z_1), \qquad z_0, z_1 \in D.$$

Theorem 9.10. For any two distinct points z_0 , z_1 in the open unit disk \mathbb{D} , there is unique shortest curve in \mathbb{D} from z_0 to z_1 in the hyperbolic metric, namely, the arc of the circle passing through z_0 and z_1 that is orthogonal to the unit circle.

Definition 9.11. The paths of shortest hyperbolic length between points are called **hyperbolic geodesics**. The hyperbolic geodesics play the role that straight lines play in the Euclidean geometry of the plane. They satisfy all the axioms of Euclidean geometry except the parallel axiom.

Theorem 9.12. Every analytic function w = f(z) from the open unit disk \mathbb{D} to itself is a contraction mapping with respect to the hyperbolic metric ρ ,

$$\rho(f(z_0), f(z_1)) \le \rho(z_0, z_1), \qquad z_0, z_1 \in \mathbb{D}.$$

Further, there is a strict inequality for all points $z_0, z_1 \in \mathbb{D}, z_0 \neq z_1$, unless f(z) is equality for all $z_0, z_1 \in \mathbb{D}$.

Definition 9.13. A geodesic triangle is an area bounded by three hyperbolic geodesics. Since the hyperbolic geodesics and the angles between then are preserved by conformal self-maps of \mathbb{D} , we can map any geodesic triangle to a triangle with vertex at 0 and with the same angles between sides.

Definition 9.14. Recall that the chordal metric on \mathbb{C} by the Euclidean metric of the sphere via the sterographic projection is given explicitly by

chordal distnace from
$$z$$
 to $w = \frac{2|z-w|}{\sqrt{1+|z|^2}\sqrt{1+|w|^2}}$

The infinitesimal form of this metric is $2|dz|/(1+|z|^2)$. If γ is a path in \mathbb{C}^* , its length in the spherical metric is

spherical length of
$$\gamma = 2 \int_{\gamma} \frac{|dz|}{1+|z|^2} = 2 \int \frac{|\gamma'(t)|}{1+|\gamma(t)|^2} dt$$

This is the length of the corresponding path on the unit sphere in \mathbb{R}^3 . The **distance from** z_1 to z_2 in the **spherical metric** is defined to be the infimum of the spherical lengths of the paths joining z_1 to z_2 .

Remark. Since the cordal metric is invariant under rotations of the sphere, so is the spherical metric, and consequently, the lengths of paths and the distances between points in the spherical metric and invariant under rotations. It is not difficult to show that the geodesics in the spherical metric correspond to great circles on the sphere, and the sum of the angles of a geodesic triangle is strictly greater than π .

Remark. We summarize the relationship between complex analyis and Euclidean, spherical, and hyperbolic geometries.

Geometry	Euclidean	Spherical	Hyperbolic
Infinitesimal length	dz	$\frac{2 dz }{1+ z ^2}$	$\frac{2 dz }{1- z ^2}$
Oriented isometries	$e^{i\varphi}z+b$	rotations	conformal self-maps
Curvature	0	+1	-1
Geodesics	lines	great circles	circles \perp unit circle
Angles of triangle	π	$>\pi$	$<\pi$
Disk circumference	$2\pi\rho$	$2\pi\rho - \frac{\pi\rho^3}{3} + \mathcal{O}(\rho^5)$	$2\pi\rho + \frac{\pi\rho^3}{3} + \mathcal{O}(\rho^5)$

10 Harmonic Functions and the Reflection Principle

10.1 The Poisson Integral Formula

Definition 10.1. We define the **Poisson kernel function** to be

$$P_r(\theta) = \sum_{k=-\infty}^{\infty} r^{|k|} e^{ik\theta}.$$

For each fixed $\rho < 1$, this series converges uniformly for $r \leq \rho$ and $-\pi \leq \theta \leq \pi$, by the Weierstrass *M*-test, since then $|r^{|k|}e^{ik\theta}| \leq \rho^{|k|}$.

Remark. We see that the trigonometric polynomial $h(e^{i\theta}) = \sum_{k=-N}^{N} a_k e^{ik\theta}$ has the (unique) harmonic extension

$$\tilde{h}\left(re^{i\theta}\right) = \sum_{k=-N}^{N} a_k r^{|k|} e^{ik\theta}$$

We capture the coefficient a_m by multiplying $h(e^{i\theta})$ by $e^{-im\theta}$ and integrating. The orthogonality relations for complex exponentials (Section 6.6) yield

$$a_m = \int_{-\pi}^{\pi} h\left(e^{i\theta}\right) e^{-im\theta} \frac{d\theta}{2\pi}$$

Substituting this expression into the formula for $\tilde{h}(re^{i\theta})$, we obtain

$$\tilde{h}\left(re^{i\theta}\right) = \sum_{k=-\infty}^{\infty} \left(\int_{-\pi}^{\pi} h\left(e^{i\theta}\right) e^{-ik\varphi} \frac{d\varphi}{2\pi}\right) r^{|k|} e^{ik\theta} = \int_{-\pi}^{\pi} h\left(e^{i\theta}\right) \left[\sum_{k=-\infty}^{\infty} r^{|k|} e^{-ik\varphi} e^{ik\theta}\right] \frac{d\varphi}{2\pi}.$$
(10.1)

In terms of the Poisson kernel, the formula for the harmonic extension $\tilde{h}(re^{i\theta})$ becomes

$$\tilde{h}\left(re^{i\theta}\right) = \int_{-\pi}^{\pi} h\left(e^{i\theta}\right) P_r(\theta - \varphi) \frac{d\varphi}{2\pi}, \qquad re^{i\theta} \in \mathbb{D}.$$
(10.2)

If we make a change of variable $\varphi \to \theta - \varphi$ and use the 2π -periodicity of $P_r(\theta)$, we obtain an alternative form of (10.2),

$$\tilde{h}\left(re^{i\theta}\right) = \int_{-\pi}^{\pi} h\left(e^{i(\theta-\varphi)}\right) P_r(\varphi) \frac{d\varphi}{2\pi}, \qquad re^{i\theta} \in \mathbb{D}.$$
(10.3)

Lemma 10.2. Let $P_r(\theta)$ be the Poisson kernel function defined by (10.1). Then the following are true:

(a)
$$P_r(\theta) = \frac{1 - |z|^2}{|1 - z|^2} = \frac{1 - r^2}{1 + r^2 - 2r\cos\theta}$$
 for $z = re^{i\theta} \in \mathbb{D}$;
(b) $P_r(\theta) = 1 + 2\text{Re}\left(\frac{z}{1 - z}\right) = \text{Re}\left(\frac{1 + z}{1 - z}\right)$ for $z = re^{i\theta} \in \mathbb{D}$;

(b)
$$\Gamma_r(\theta) = \Gamma + 2\pi e^{-1} \left(1 - z\right) = \pi e^{-1} \left(1 - z\right)$$

(c) $\int_{-\pi}^{\pi} P_r(\theta) \frac{d\theta}{2} = 1;$

- (c) $\int_{-\pi}^{\pi} f_r(\theta) 2\pi^{-1}$; (d) $P_r(\theta) > 0, -\pi \le \theta \le \pi$;
- (e) $P_r(-\theta) = P_r(\theta), \ -\pi \le \theta \le \pi;$
- (f) $P_r(\theta)$ is increasing for $-\pi \le \theta \le 0$, and decreasing for $0 \le \theta \le \pi$;
- (g) for fixed $\delta > 0$, $\max\{P_r(\theta) : \delta \le |\theta| \le \pi\} \to 0$ as $r \to 1$.

Remark. From Lemma 10.2, (10.2) becomes

$$\tilde{h}\left(re^{i\theta}\right) = \int_{-\pi}^{\pi} h\left(e^{i\varphi}\right) \operatorname{Re}\left(\frac{1 + re^{i(\theta - \varphi)}}{1 - re^{i(\theta - \varphi)}}\right) \frac{d\varphi}{2\pi}.$$

Thus

$$\tilde{h}\left(re^{i\theta}\right) = \int_{-\pi}^{\pi} h\left(e^{i\varphi}\right) \operatorname{Re}\left(\frac{e^{i\varphi} + z}{e^{i\varphi} - z}\right) \frac{d\varphi}{2\pi} \qquad z \in \mathbb{D}.$$
(10.4)

If we substitute for $h(re^{i\varphi})$ a real-valued trigonometric polynomial $u(e^{i\varphi})$ in this formula, we may take real parts after integrating, and we obtain

$$\tilde{u}(z) = \operatorname{Re} \int_{-\pi}^{\pi} u\left(e^{i\varphi}\right) \frac{e^{i\varphi} + z}{e^{i\varphi} - z} \frac{d\varphi}{2\pi}, \qquad z \in \mathbb{D}.$$
(10.5)

The integral depends analytically on the parameter z. Thus (10.5) expresses $\tilde{u}(z)$ as the real part of an explicit analytic function.

Definition 10.3. Consider an arbitrary continuous complex-valued function $h(e^{i\theta})$ on the unit circle. We define the **Poisson integral** $\tilde{(}h)(z)$ of $h(e^{i\theta})$ to be the function on the open unit disk \mathbb{D} given by

$$\tilde{h}(z) = \int_{-\pi}^{\pi} h\left(e^{i\theta}\right) P_r(\theta - \varphi) \frac{d\varphi}{2\pi}, \qquad z = re^{i\theta} \in \mathbb{D}.$$
(10.6)

This is just (10.2) and it can be written as (10.3). Formula (10.4) still holds, and for real-valued continuous functions $u(e^{i\varphi})$, formula (10.5) holds.

Remark. The correspondence $h \to \tilde{h}$ is linear, that is, the Poisson integral of $c_1h_1 + c_2h_2$ is $c_1\tilde{h_1} + c_2\tilde{h_2}$. Also, observe that the maximum principle holds, in the sense that if $|h(e^{i\theta})| \leq M$ for all θ , then $|\tilde{h}(z)| \leq M$ for all $z \in \mathbb{D}$.

Theorem 10.4. Let $h(e^{i\theta})$ be a continuous function on the unit circle. Then the Poisson integral $\tilde{h}(z)$ defined by (10.6) is a harmonic function on the open unit disk that has boundary values $h(e^{i\theta})$, that is, $\tilde{h}(z)$ tends to $h(\zeta)$ as $z \in \mathbb{D}$ tends to $\zeta \in \partial D$.

10.2 Characterization of Harmonic Functions

Definition 10.5. A **Dirichlet problem** for a domain U with boundary ∂U is to extend a given function $f(\zeta)$ on ∂U to a harmonic function $\tilde{f}(z)$ on U, so that the harmonic extension $\tilde{f}(z)$ has boundary values $f(\zeta)$.

Theorem 10.6. Let h(z) be a continuous function on a domain D. Then h(z) is harmonic on D if and only if h(z) has the mean value property on D.

10.3 The Schwarz Reflection Principle